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**School of Chemical Technology
Degree Programme of Chemical Technology**

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**Particle movement and mixing in three-phase gas-liquid-solid
fluidized bed**

**Master's thesis for the degree of Master of Science in Technology
submitted for inspection, Espoo, 10 November, 2015.**

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Title of thesis Particle movement and mixing in three-phase gas-liquid-solid fluidized bed

Department Department of Biotechnology and Chemical Technology

Professorship Chemical Engineering

Code of professorship KE-42

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Date 10.11.2015

Number of pages 83

Language English

Abstract

The objective of this thesis is to study the movement and the mixing of the particles in the liquid-solid and the gas-liquid-solid fluidization as well as to provide validation data of the fluidized bed behavior. The results are used for validation in CFD (computational fluid dynamics) models at a concurrent PhD thesis.

The experiments were made in a rectangular 10 cm by 10 cm column. The used liquid and gas phases in the experiments were tap water and compressed air, respectively. The solid particles in the fluidized bed were 2.3 mm diameter glass beads. The experiments were carried out varying the flow rates of the gas and liquid entering the column. The bed height, the pressure difference in the bed, the superficial flow velocities of the gas and the liquid, and the particle movement patterns were observed and measured during the experiments. The particle movement and the bubble flow regimes were analyzed from video recording.

In the experiments the minimum fluidization points at the different superficial gas velocities were measured. In addition, the solid and the gas-hold-up as well as the bed expansion were calculated from the measurements for different superficial gas and liquid flow velocities.

It was found out that superficial liquid velocity at minimum fluidization point is higher with zero or diminutive gas flow than when the gas flow is larger. In addition, when superficial gas flow is larger the superficial liquid velocity at minimum fluidization point is independent on gas flow rate. It was found that the bed expansion is rather independent on superficial gas flow velocities when superficial liquid flow is smaller. However when superficial liquid flow is larger the increase in superficial gas flow decreases the bed expansion. With this column and particle settings the bubble coalescence was vigorous. With all superficial gas and liquid used in the experiments the bubble flow regime was either in coalesced bubble flow or slug flow regime.

Keywords

Three phase fluidization, Gas-liquid-solid fluidization, Liquid-solid fluidization, Particle movement, Bubble flow regimes, Fluidized bed expansion

Tekijä Henrik Heino

Työn nimi Partikkelien liike ja sekoittuminen kolmefaasi kaasu-neste-kiinteä - fluidisaatiossa

Laitos Biotekniikan ja kemian tekniikan laitos

Professuuri Kemian laitetekniikka

Professuurikoodi KE-42

Työn valvoja Prof. Ville Alopaeus

Työn ohjaaja(t)/Työn tarkastaja(t) DI Olli Sorvari

Päivämäärä 10.11.2015

Sivumäärä 83

Kieli Englanti

Tiivistelmä

Tämän diplomityön tavoitteena on tutkia kiinteiden partikkelien liikettä ja sekoittumista neste-kiinteä - ja kaasu-neste-kiinteä - fluidisaatiossa, sekä tuottaa validointidataa fluidisaation käyttäytymisestä. Tuloksia hyödynnetään CFD (Computational fluid dynamics, laskennallinen virtaussimulointi) malleissa samanaikaisessa väitöskirjassa.

Tämän työn kokeet suoritettiin neliskulmaisessa 10 cm kertaa 10 cm kolonnissa. Kokeissa käytetty kaasufaasi oli hanavesi ja kaasufaasi paineilma. Pedin kiinteät partikkelit olivat lasikuulia 2,3 mm halkaisijalla. Kokeet tehtiin vaihtelemalla kolonniin tulevan kaasun ja nesteen virtausnopeuksia. Kokeiden aikana tarkkailtiin ja mitattiin pedin korkeutta, paine-eroa pedissä, nesteen ja kaasun tyhjäputkinopeutta sekä partikkelien liikettä pedissä. Partikkelien liikettä ja kuplien virtausregiimejä analysoitiin videotallenteista.

Kokeiden mittaustuloksista määritettiin kaasuvirtauksen vaikutus minimifluidisaatiopisteeseen. Myös kiinteän ja kaasun tilavuusosuus sekä pedin laajeneminen laskettiin eri kaasun ja nesteen virtaamilla.

Kokeissa havaittiin, että kaasun tyhjäputkinopeuden vaikutus minimifluidisaatiopisteeseen on suhteellisen pieni suurimmilla kokeissa käytetyillä kaasun virtaamilla, mutta kaasun nopeuden lähentyessä nollaa on nesteen tyhjäputkinopeus minimifluidisaatiopisteessä huomattavasti korkeampi. Pedin laajenemista mittaavissa kokeissa havaittiin, että kokeissa käytetyillä pienemmillä nesteen virtaamilla kaasun virtaaman vaikutus pedin laajenemiseen on hyvin pieni, kun taas suuremmilla nesteen virtaamilla suurempi kaasun tyhjäputkivirtaus pienentää pedin laajenemista. Kokeissa käytetyllä kolonnilla ja partikkeleilla kuplien yhdistyminen oli hyvin voimakasta. Havaittiin, että kaikilla käytetyillä kaasun ja nesteen virtausnopeuksilla kuplien virtausregiimi oli joko yhdistyväkuplavirtaus- tai tulppavirtausregiimi.

Avainsanat Kolmifaasifluidisaatio, Kaasu-neste-kiinteä –fluidisaatio, Neste-kiinteä –fluidisaatio, Partikkelien liike, Kuplien virtausregiimit, Fluidisaatiopedin laajeneminen

Acknowledgements

I would like to thank my supervisor Professor Ville Alopaeus for offering the Thesis position and all the guidance during the Thesis. I would also like to thank my instructor Olli Sorvari letting me work on my own pace and always giving a helping hand whenever needed. In addition, I would like to thank everybody in the Chemical Engineering laboratory for all the help they offered me.

I would like to also thank Michelle Lai for help with language troubles and for proofreading.

Special thanks goes to my brother Juhana and sister Anna-Maria for always helping me in whatever I asked and to my dad Seppo for guiding, encouraging and supporting me in everything I have done. Above all, I want to thank my mother Lea for everything she ever did for me.

Espoo, Finland, 10 November 2015

Henrik Heino

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Nomenclature

a'	a factor related to the variables of the solids
A_p	area below the voidage-velocity expansion curve [m ²]
A_R	corresponding area of A_p in real fluidization [m ²]
Ar	Archimedes number
A_{sph}	surface area of sphere [m ²]
A_{part}	surface area of a particle [m ²]
\bar{c}	average concentration of tracer particles in the bed
d_n	mean bubble size [m]
d_p	particle diameter [m]
f	friction factor / volume fraction
$f(\varepsilon)$	drag force ratio
F_g	gravitational force [N]
F_k	drag force [N]
F_{ks}	effective drag force [N]
F_s	buoyancy [N]
Fr	Froude number
g	acceleration of gravity [m/s ²]
g_c	conversion factor
H_f	height of the fluidized bed [m]
H_0	height of the static bed [m]
H, L	effective height of the bed [m]
L_{mf}	height of the fixed bed at minimum fluidization conditions [m]
m	mass [g]
M	mixing index
n_i	number of tracer particles in a sample

n_t	number of tracer particles in the whole bed
n_{it}	number of particles in a sample
Re	Reynolds number
S	cross-section area of the column [m ²]
U	velocity [m/s]
U^s	superficial fluid velocity [m/s]
U_b	bubble rising velocity [m/s]
U_{mf}^s	superficial fluid velocity at minimum fluidization conditions [m/s]
Δp_{cb}	pressure drop of the channeling bed [Pa]
Δp_t	pressure drop [Pa]
$-\frac{dP}{dz}$	static pressure gradient
V	superficial velocity of fluid [m/s]
W	weight of the particles in the bed [g]
x_d	Channeling factor
$\bar{\rho}$	suspension density [kg/m ³]
ρ_f	density of fluid [kg/m ³]
ρ_l	density of liquid [kg/m ³]
ρ_p	density of a particle [kg/m ³]
ρ_s	density of solid [kg/m ³]
ε	voidage
ε_{mf}	overall bed void fraction at minimum fluidization conditions
ε_g	gas hold-up
ε_l	liquid hold-up
ε_s	solid hold-up
Φ_s	sphericity parameter
μ	viscosity [mPas]

Literature part

1 Introduction

Fluidization is a process where solid particles are suspended in a continuous liquid or gas phase. The fluidization process is commonly employed in a wide-range of industries, such as oil refining and energy production. This thesis focuses on fluidization processes where liquid forms the continuous phase and gas phase is non-existent or in a form of bubbles.

The liquid-solid and gas-liquid-solid fluidization technologies have been in use since the beginning of the 20th century. The earliest industrial gas-liquid-solid fluidization process was coal hydrogenation taking place in a slurry bubble column. In coal hydrogenation the pulverized coal reacts with hydrogen forming motor fuels. Utilization of the process had its prime during World War II in Germany where the production of mainly aviation fuel peaked at 4.2 million barrels. The production method was phased out after the war. The first commercial co-current gas-liquid-solid fluidization reactor was applied in hydrotreating the petroleum resins in 1968. The process is currently employed, amongst others, in hydrotreating of heavy and synthetic crude oils, and it is an important part of the oil refining plants.[1]

In a gas-liquid-solid fluidization reactor, which hydrotreats heavy hydrocarbons, the fluidized solid phase is composed of catalyst particles. The solid catalyst particles are supported by an upward flow of liquid hydrocarbons and the hydrogen, needed for hydrogenation, is fed to the bottom of the reactor co-currently with the liquid.[1]

One of the greatest advantages of the fluidized bed reactors compared to fixed bed reactors is that the fluidized bed reactors do not necessarily need to be stopped during the change of the catalyst.[1] The solid particles can be simultaneously removed and replaced while the fluidization is ongoing.

Another advantage of the fluidized beds is the effective mixing inside the catalyst bed. Consequently, the temperature differences within the bed are usually small. However, it is possible for stagnant regions to be formed within the bed in which

mixing is nonexistent. In case a stagnant region is formed in an exothermic reactor the temperature begins to rise locally due to accelerating reaction and decreased heat transfer. The condition is known as hot spot.[1]

The effective and safe exploitation of these advantages of liquid-solid and gas-liquid-solid fluidization reactors requires knowledge of the particle movement patterns. More throughout understanding would enable better design of catalyst replacement systems, lessen the risk of hazardous hot spot formation and possibly open new ways to safely increase the yield of these reactors.

The goal of this Thesis is to obtain measurement data of the liquid-solid and gas-liquid-solid fluidized bed behavior, the particle movement and particle mixing in laboratory scale column. The measurement data is used to validate CFD (computational fluid dynamics) models as a part of concurrent PhD thesis.

2 Fluidization

Fluidization is a phenomenon in which solid particles are agitated upwards by a fluid stream in a vertical column. The upward streaming fluid can be either gas or liquid. Solid particles can be anything from a powder-like substance to metal particles. Fluidization is done usually in a column with a circular cross-section but also other shapes.[2-5]

Fluid flows through a permeable distribution plate into the bed of solid particles. The distribution plate spreads the flow and holds the solid particles in a fixed state, when the fluid stream velocity is not high enough to fluidize the particles.[3,5] Normally a column incorporates a homogenization section below the distribution plate, which function is to homogenize the fluid stream along the cross-section as evenly as possible.[3] Schematic design of the fluidization column is presented in Figure 1.

Above the distribution plate there are three distinctive regions: the gas-liquid distribution region, the bulk fluidized bed region, and the freeboard region. In the distribution region, the distribution plate gives the bubbles a specific size. The

hydrodynamics in the distribution region is strongly dependent on the design of the distribution plate. The bulk fluidized bed region includes the main part of the fluidized bed, where the hydrodynamics are dependent on the operation conditions of fluidization. The freeboard region is located above the bulk fluidized bed region and containing mainly liquid, rising bubbles and only some entrained particles. With large and heavy particles the entrainment is less significant than with light and small particles.[1] Regions in the fluidized bed are also presented in Figure 1.

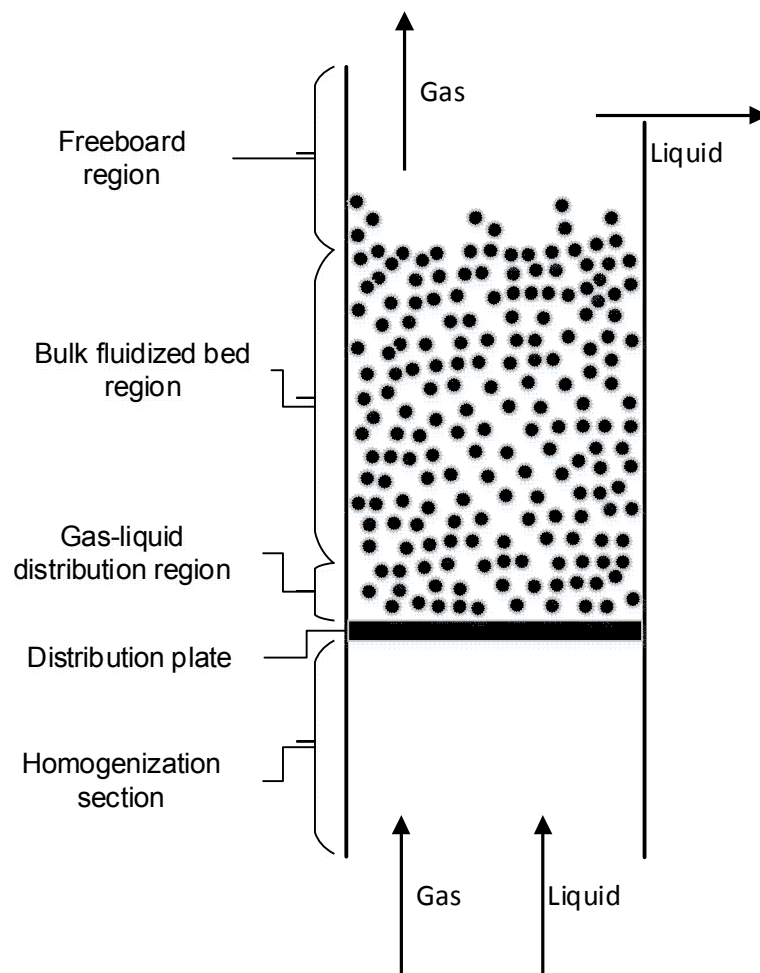


Figure 1. Fluidization column.

When the fluid starts to flow, the frictional drag between the fluid and the particles increases so that frictional drag becomes equal to the weight of the particles subtracted by buoyancy. This causes the particles to rearrange in a way that the particles generate the least resistance for the fluid flow.[6] At this point the bed is called expanded bed although the bed is not yet expanding substantially[4,7] and can even contract depending on the initial state of the bed as observed in the experiments of this thesis (paragraph 11.1). The particle bed structure continues to rearrange until it reaches the loosest form of packing. When the flow rate is further increased the particles separate from the structure, are lifted from the distribution plate, and become supported by the fluid flow i.e. the state of the solid particles change from fixed to fluidized.[6] The velocity in which this change occurs is called minimum fluidization velocity.[3]

After the minimum fluidization, the increase in the fluid velocity causes the bed to expand further. The bed keeps expanding until the fluid velocity is high enough to convey the particles out of the column. This phenomenon is called hydraulic or pneumatic transport depending on if the fluid is liquid or gas, respectively.[3]

Fluidization can be gas-solid, liquid-solid or gas-liquid-solid. Generally, the concept is the same in all fluidization: gas or liquid is fed from the bottom to the bed of solid particles that causes the particles to lift up from the surface when the velocity is fast enough. Nevertheless there are still some differences in how the fluidization behaves amongst different fluids. As an example, in liquid-solid fluidization the particles are distributed more homogeneously whereas in gas-solid fluidization the particles tend to have more aggregative behavior.[4]

3 Gas-Liquid-Solid fluidization

In gas-liquid-solid fluidization all the phases, gas, liquid and solid are present. In this type of fluidization, the solid particles are suspended in the gas or liquid phase. Gas-liquid-solid fluidization has multiple operating modes. These modes are defined by which phase is continuous, whether the gas and liquid phases flow counter-currently or co-currently, and where the phases are fed to the column.[1,8]

There are four major gas-liquid-solid fluidization modes. The modes are presented in Figure 2. The most studied mode is fluidization with co-current flow and liquid as the continuous phase (E-I-a). The solid particles are supported by liquid flow and gas flows in a form of discrete bubbles. This is generally called gas-liquid fluidization. If the gas flow is increased in this fluidization mode, the system will first approach the transitional state, where it is unclear if the continuous phase is liquid or gas. When the gas flow is increased further the continuous phase of the system will become gas. After the continuous phase has changed, the gas-liquid-solid fluidization mode will be considered distinct from each other (E-I-b).[8]

Another widely studied type of gas-liquid-solid fluidization is counter-current fluidization with continuous gas phase (E-II-b). This type of fluidization is called turbulent contact absorber (TCA). In the system, liquid is sprayed from the top of the column to the bed that is fluidized by a gas stream. An advantage in this type of fluidization is the excellent gas-liquid contact. Flow rates for both gas and liquid are much higher compared to packed bed counter-current systems.[8]

The fourth type of gas-liquid-solid fluidization is counter-current fluidization where the continuous phase is liquid (E-II-a). This is called inverse three-phase fluidization. In this fluidization, the density of the solid particles is lower than the density of the liquid, causing the solid particles to float on the surface of the stagnant liquid phase. The fluidization state is caused by the liquid flow directed downward towards the bottom of the column. The gas is fed from the bottom against the liquid flow. At lower gas flow rates the gas appears in the form of discrete bubbles. If the gas flow is increased, the system will first enter a transition state and, with even higher velocities, the gas phase becomes the continuous phase. A column in this mode is considered as a turbulent contact absorber.[8]

Mode	I-a	I-b	II-a	II-b
Schematic Diagram of Gas-Liquid-Solid Fluidization				
Continuous Phase	Liquid	Gas	Liquid	Gas
Flow Direction	Cocurrent Up-flow		Countercurrent flow	

Figure 2. Fluidization operating modes.[8]

3.1 Co-current bubble flow regimes

In the co-current gas-liquid-solid fluidization, four distinct bubble flow regimes are observed. According Zhang et al. these flow regimes are dispersed bubble flow regime, discrete bubble flow regime, coalescent bubble flow regime and slug flow regime.[9] The regimes are mapped in Figure 3 and shown in Figure 4. The demarcation between the flow regimes vary with the design of the column and the operating conditions (for instance the shape as well as the size of the column, distributor design, liquid and solid properties)[10].

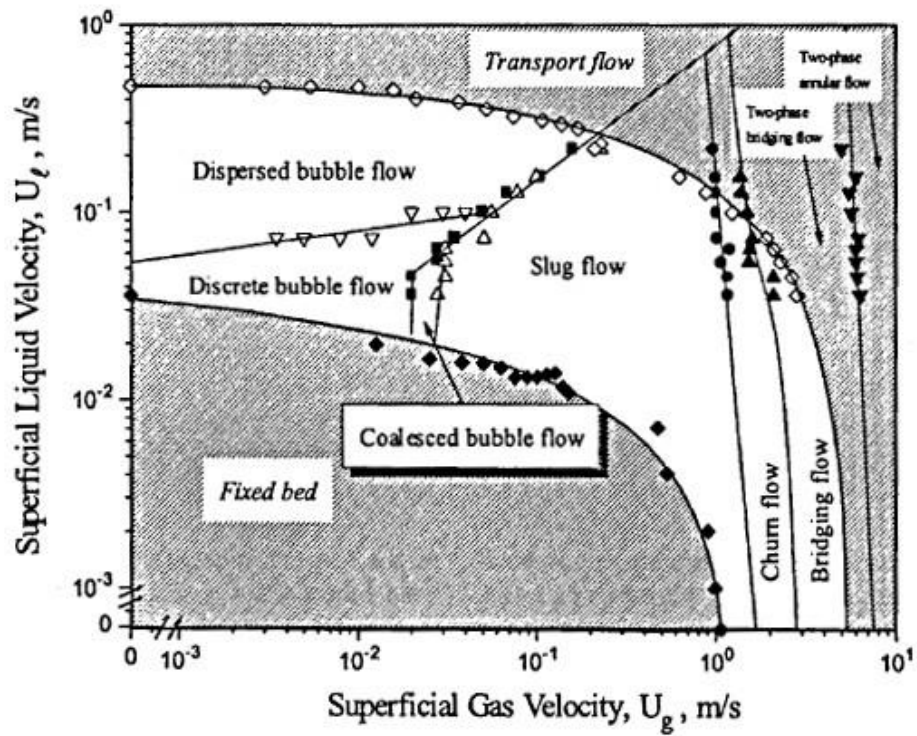


Figure 3. Flow regime map.[9]

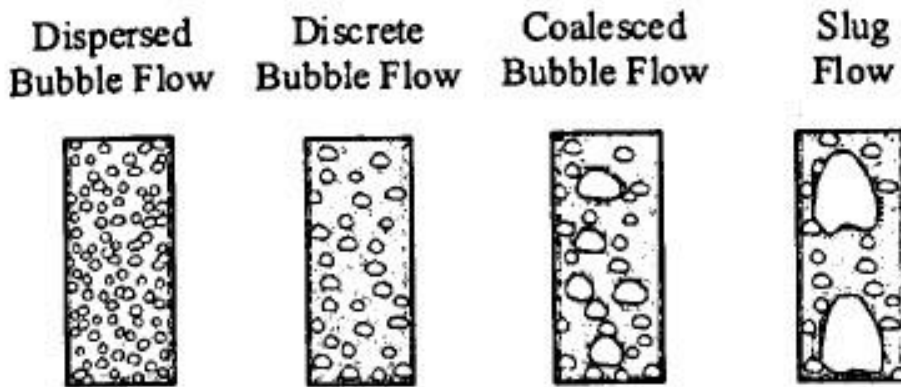


Figure 4. Bubble flow regimes.[9]

Chen et al. contemplated the bubble flow regimes in gas-liquid column and gas-liquid-solid column with solid hold-up up to 10 %. Chen et al. observed that with these solid hold-ups, the bubble flow structure being rather similar to systems

without solids, only the flow structure sizes were changing. Chen et al. wrote a study concerning the three different bubble flow regimes: dispersed bubble flow, vortical-spiral flow and turbulent flow regime. From which the vortical-spiral flow and turbulent flow regime are also considered as sub-regions of the coalesced bubble regime.[10]

Discrete bubble flow occurs in the fluidized state with low liquid flow rates. When the gas flow is introduced, a small amount of small bubbles appear. Bubble size distribution is narrow and the sizes are strongly depending on the distributor design. When gas flow is increased enough, the bubbles start to coalesce.[9]

In the dispersed bubble flow regime the bubbles are small and the sizes are rather uniform in the whole column.[10,11] Bubbles also tend to rise rectilinearly in the column. The liquid flows downward mostly straight between the rising gas bubble streams.[10] In the dispersed bubble flow regime the liquid flow velocity is higher than in the discrete bubble flow. What separates the dispersed flow regime from discrete flow regime is that the bubble size formation is rather independent of distributor.[9]

What regimes there are in the system depends strongly on the solid particle sizes and densities. For example in water-air-glass sphere system the discrete bubble flow regime does not exist if the particles are small because coalescing of bubbles starts immediately when the gas flow is introduced. In the systems with larger particles, more bubble break up is occurring. This indicates that the coalescent bubble flow regime is emerging in narrower gas and liquid flow velocity interval.[9]

In the vortical-spiral flow regime the superficial gas velocity is higher than in dispersed bubble flow regime. When the gas velocity is increased from the velocities used in the dispersed bubble flow regime, the bubbles start to migrate towards the center of the column in clusters and start the spiral motion. At this point, the coalescence of the bubbles is not yet significant. When the gas flow is further increased, the bubbles start to coalesce and break-up while the clusters diminish and the spiral motion intensifies.[10]

In the turbulent flow regime there are large bubbles separated by a certain distance from each other. Turbulent flow regime emerges when the bubbles coalesce intensively and, consequently, interrupts the continuous spiral flow pattern of the central bubble flow. The momentum of the bubbles wakes are transferred to surrounding liquid and the liquid mixing is caused mainly by the bubble wakes. The liquid flow pattern is much more chaotic than in the vortical spiral flow regime. The mixing in the top and the bottom of the column is not as rapid in turbulent flow regime as in vortical spiral flow regime.[10]

Slug flow regime is occurs when the gas velocity is increased enough.[9] In the slug flow regime, the bubbles are even larger[11] and the shape of the bubbles resemble bullets[9]. The diameter of the bubble can be the same as the diameter of the column.[11] In addition to these large bubbles, in slug flow regime there are also many smaller bubbles, which follow the larger ones.[9] Slugging does not occur in large diameter columns.[1]

3.2 Flow regions in vortical-spiral flow regime

Larachi et al. identified three different flow regions in gas-liquid-solid fluidization vortical-spiral flow regime: fast bubble flow region, descending flow region and vortical flow region.[12] In addition to those Tzeng et al. observed in their study the central plume region in the center of the column.[10,13] The flow regions are presented in Figure 5.

It is important to acknowledge that the boundaries between regions are not exact and peculiar behavior in one region can occur also in other regions.[12]

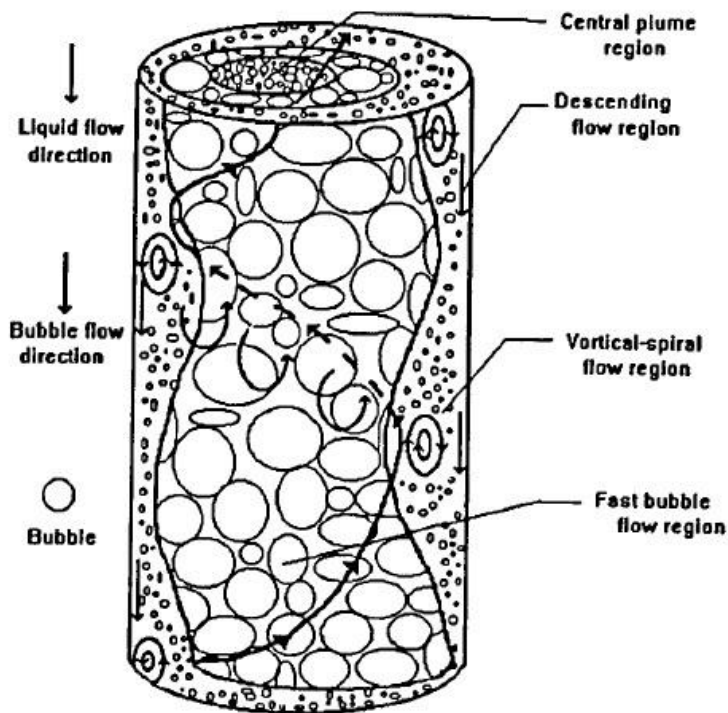


Figure 5. Flow regions in the vortical-spiral flow regime.[10]

3.2.1 Descending flow region

When particles are moving downwards they seem to prefer the regions near the walls. This region near to the walls is called descending flow region. While the solid particles descend they also tend to migrate slightly towards the center of the column, where - at some point - they will catch another bubble wake and, thus, changing the movement direction upwards again.[12] In the descending flow region, there is no noticeable zigzag motion like in upward flows, however in the descending flow region the flow has a distinguishable spiral behavior.[10,12]

At the low superficial gas flow velocities in the descending flow region is free of bubbles, whereas higher velocities the descending flow region contains also small bubbles. These bubbles stays either stationary or are moving depending on the bubble size and liquid flow.[13]

3.2.2 Vortical flow region

In the area between the fast-bubble flow region and descending flow region there is a region called vortical flow region.[10,12] In this region the particles have just exited the fast-bubble flow and have not yet moved into the descending flow. The particles normally stay in the vortical flow region less than a second and the movement of the particles are very rapid and intense. It is very difficult to mark boundaries, especially where the vortical flow region ends and where the descending flow region begins, because of the dynamic nature of the flows.[12] So the entire region moves back and forth according to the neighboring fast bubble flow region.[10]

The vortices usually form near the free bed surface and, from there, tend to move downwards until at some point they disappear. When the superficial gas velocity is increased the vortices become more unstable. The size of the vortex depends strongly on the superficial gas velocities, the size increases with the gas flow velocity until the point of bubbly-churn turbulent transient velocity, after which the size stays rather constant.[13] The mixing of the phases is extensive in this region.[10]

3.2.3 Fast-bubble flow region

The remarkable bubble coalescence and break-up is occurring in the fast bubble flow region. The bubble break up is caused partly by local flow turbulences. The bubbles are moving in a wavelike motion in a two-dimensional column where one dimension was considerably smaller than other dimensions. When experiments were done in three-dimensional column the bubbles moved in a spiral like motion. Bubbles tend to move in clusters at lower superficial gas flow velocities or as coalesced bubbles in higher superficial gas flow velocities.[10,13] The behavior of fast bubble flow region dictates the macro hydrodynamics of the flow system in vertical-spiral flow regime.[10]

According to Chen et al., when increasing the superficial gas velocity, the width of the fast-bubble region increases linearly until a certain point where the width remains constant. The maximum width of the fast bubble flow region is of the same order as the large coalescent bubbles in the turbulent flow regime. Increasing the

superficial gas velocity also increases the pitch of the spiral motion to the point where the pitch starts to decrease with the further increase in the gas velocity.[10]

Respectively, the increase in superficial liquid velocity slows down the bubble coalescence and decreases the width of the fast bubble flow region. Increase in superficial liquid flow velocity also decreases the spiral pitch. In addition, the increase of the liquid velocity decreases the sizes of the bubbles.[10]

3.2.4 Central plume region

Tzeng et al. observed that the central plume region exists in the center of the column core as well. This central plume region is surrounded by the fast bubble flow region. In the central plume region, the bubble sizes are more uniform compared to bubbles in the fast bubble flow region. To add, in the fast bubble flow region, the bubbles interact more intensively with each other than in central plume region, therefore the bubble coalescence and break-up is more common in the fast bubble flow region than in central plume region. In high superficial gas velocities, the coalescence still occurs, however more in the vertical direction, rather than lateral as in fast-bubble flow region.[10,13]

3.3 Bubble wake model

The wake phenomena plays a significant role in the understanding the bed hydrodynamics in gas-liquid-solid fluidized bed. The wake phenomena is responsible for a large part of the particle movement in the vertical direction and, thus, induces mixing in the fluidized bed considerably. There are two regions of the wake that moves the particles: a stable solid region, where the particles are moved upwards following the leading bubble, and shedding wake region, where the solids are pushed towards the liquid-solid emulsion. The shedding region is able to collect particles from the stable region, so that the particles will not reach the surface of the bed every occasion. Vice versa, the particles can move to the stable solid region, where the particles are transferred towards the surface of the bed. After the particles are shed from the wake they start to move downwards.[12]

By forming a distribution for the axial location where the particle is shed from the wake, it can be seen that the wake shedding tends to be more intensive when

moving further away from distribution plate. Half of the shedding occurs in the upper third of the bed. For wake phenomena, it is also peculiar that the bubble and, thus, the wake velocity varies during the rise as well. This is due to the bubbles interactions with other bubbles such as bubble coalescence and bubble break-ups.[12] In addition, when the bubble is accelerating while ascending, the wake grows in size and collects more particles.[1]

It is possible to contour the distinct areas in the cross-section, where the bubble wakes are active. In these areas, the particle movement upward is also significant. The particles near the distribution plate, when caught by the wake, first moves towards the center of the column while traveling up.[12] The wake shedding phenomena is strongly connected to the flow path the bubble takes. For example, the interaction with vortices causes particles to shed from alternating sides, which again causes the bubble to move in zigzag motion.[1] Interaction with other bubbles can also cause zigzag motion.[12]

To conclude, the bubble wake is significant factor when assessing phenomena in the fluidized bed such as solids mixing, particle entrainment into the freeboard, and bed contraction when introducing the first bubbles in the system.[1] When a bubble is rising upwards in gas-liquid-solid fluidized bed, the bubble is followed by a liquid having a flow velocity higher than the average liquid velocity in the column. Consequently, the liquid following the bubbles have shorter residence time than the water not following the bubbles. This causes the bed to contract until the point of critical gas flow, after which the bed starts to expand.[14]

3.4 Bubble characteristics

The performance of the fluidization is strongly determined by the behavior of the bubbles in the gas-liquid-solid fluidization. Knowledge of the hydrodynamic properties including bubble size, bubble rise velocity, velocity distribution and bubble distribution is an important part in understanding the behavior of the gas-fluid-solid fluidized bed. This is, because they define in some extent the hydrodynamic properties like liquid flow patterns, solids mixing and gas-liquid interfacial area.[15]

Sizes of the holes in the distribution plate is a significant factor when defining the initial size of the bubbles created. Large holes produces larger bubbles, which leads to greater heterogeneity in the bed and the small holes generates smaller bubbles, which smaller bubbles has tendency to merge into larger bubbles while moving upwards losing the benefit for the smaller holes if the bed is high.[16] Other factors defining the initial bubble size are buoyancy, viscous drag, surface tension and inertia. Bubble collision with single particles in the bed also induce breaking up the bubbles, if the particle diameter is larger than the diameter of the bubble. If bubble is penetrated with multiple particles- as usually is in fluidized bed- it induces bubble instability and, thus, also bubble breakage.[1]

The increase in liquid flow velocity decreases the bubble size until a certain point in which the increase of the liquid flow velocity is no more effective.[1] In the dispersed flow regime, the bubble size reaches minimum near the minimum fluidization velocities. When the liquid velocity is increased from that the bubble size becomes larger.[17]

The bed expansion parameter H/H_0 is the ratio between fluidized bed height and static bed height. It is related to solid hold-up and to the mean bubble size in the bed. In the dispersed bubble flow regime, the mean bubble size varies only slightly when bed expansion parameter increases. On the other hand, in the coalescent bubble flow regime the mean bubble size increases substantially when the bed expansion parameter increases. In the slug flow regime, the bubble size increases moderately with the increase in bed expansion parameter.[15]

The increase in bubble size above the distributor is due to the bubble coalescence. The bubble coalescence is more intense in the bed of small particles.[1] In gas-liquid-solid fluidization the bubble size distribution varies substantially with the axial location and with flow regime. According Matsuura and Fan, the effect the particle size has on the bubble size and bubble size distribution is rather small. However, the flow regime has a great effect on the mean bubble size.[15]

In the gas-liquid-solid fluidized bed, the bubble rising velocities depends strongly on the size of the bubble and, therefore, also on the flow regime.[1] In the slug flow regime, the bubble rising velocity can be estimated with equation 1. It is also

noticeable that the bubble rising velocities behind the slugs are higher than similar bubbles in dispersed bubble flow regime.[15]

$$U_b = 3.4\sqrt{gd_n}$$

1

Where d_n is the mean bubble size.

The distributions of the bubble rise velocities are rather similar in coalesced bubble flow regime and in dispersed bubble flow regime. The small difference between velocity distribution curves with the dispersed flow regime and coalescent flow regime demonstrated that the coalescent flow regime the bubble velocity is slightly faster in the coalescent flow regime and the velocities are more narrowly distributed in the dispersed flow regime.[15]

3.5 Particle velocity distributions

In the fast-bubble flow region and in the descending flow region, the particle movement has a longer amplitude than in the vortical flow region. These two regimes comprises the gulf-streaming (gross circulation) in the bed.[12]

Larachi et al. drew a Figure 6 of average velocities of the particles in axial direction highlighted by different colors. The figure clearly shows the velocity vector distribution. Whereas in the middle of the column the rapidly upward moving particles comprises the fast-bubble flow region, the descending particle velocities are greatest in the descending flow regions. Between these regions there is a distinguishable flow inversion region, the vortical flow region, where the particle velocities in the axial direction are close to zero.[12]

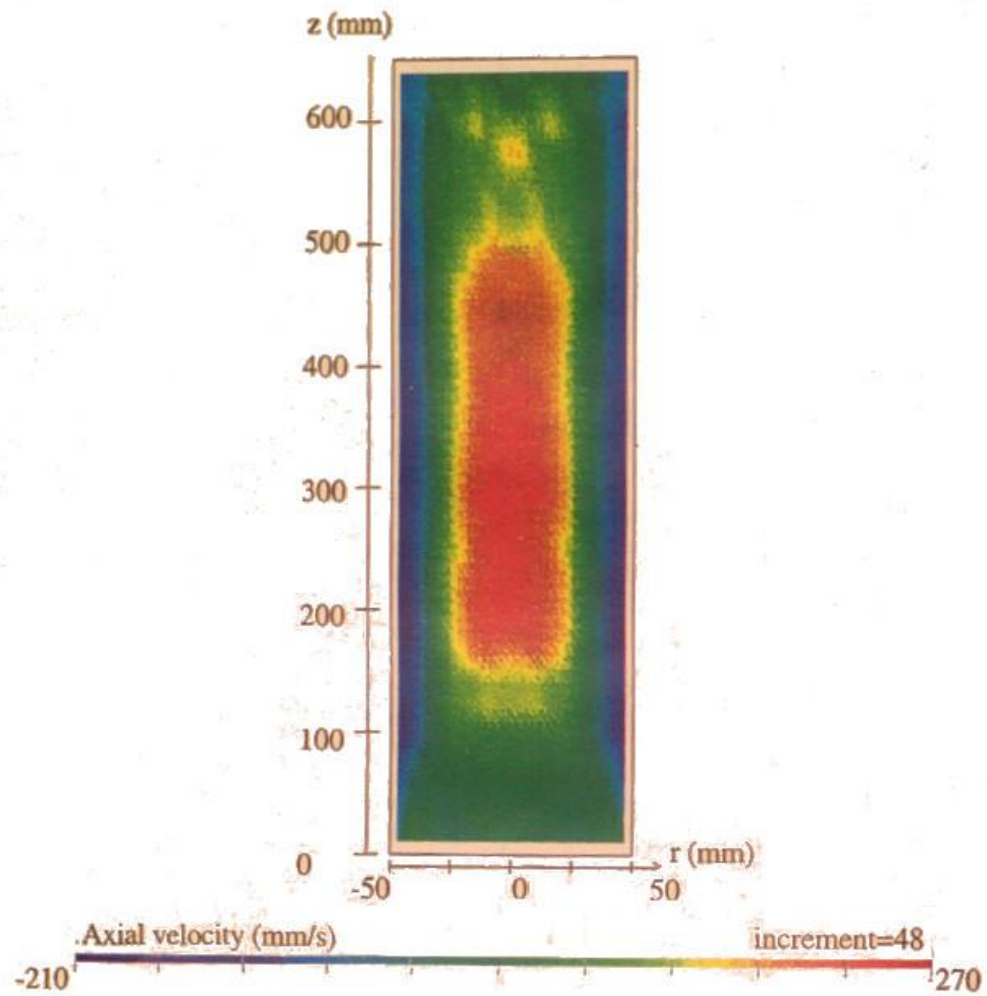


Figure 6. Average velocities of the particles in axial direction.[12]

The vortical-spiral flow regime in the bottom of the bed there is the establishing flow region or the gas-liquid distribution region where average particle velocities in axial direction are still closer to zero and descending, boundaries of vortical and fast-bubble flow region are not yet visible. Larachi et al. states that in this establishing flow region, the descending flow near the wall forces the bubbles to move towards the center of the column, where they start to coalesce into larger bubbles. At that point the larger bubbles are able to carry the particles in their wake, causing particles to accelerate upwards. Above the establishing flow region there is a region where flow is fully developed and the particle velocities in the axis

direction is relatively stable. Above the fully developed region there is a region called disengagement part. The disengagement part is where the axial particle velocities decelerates from the velocities in the middle and particles change direction and start flowing downwards.[12]

Larachi et al. measured the turbulence in two directions: axial and radial. Intensive turbulence in the radial direction occurs in the fast-bubble flow region where the particles are swinging and rocking back and forth. The most intensive turbulence in radial direction is the decelerating zone where the wakes discharge the rising particles and the particles change in flow direction. In the axial direction, the turbulence is the most intensive in the vortical flow region between the fast-bubble flow region and descending flow region.[12]

3.5.1 Channeling

Channeling is a phenomenon where the fluid and particle flow velocities are not distributed evenly in the cross-section of the column. In fluidization the channeling occurs when a great portion of the fluid passes through the fluidized bed within a small cross-sectional area and only a small portion of the fluid passes through the bed evenly.[16,18] Channeling fluidized bed is illustrated in Figure 7. The uneven velocity distribution is a significant factor when characterizing the hydrodynamics and mixing characteristics of the fluidized bed[13].

Initially, channeling occurs due to the uneven pressure profile in the distribution plate. Consequently, when maldistribution occurs it establishes the path of least resistance for the fluid creating a channel where the fluid has greater flow velocity than the rest of the bed.[16,18]

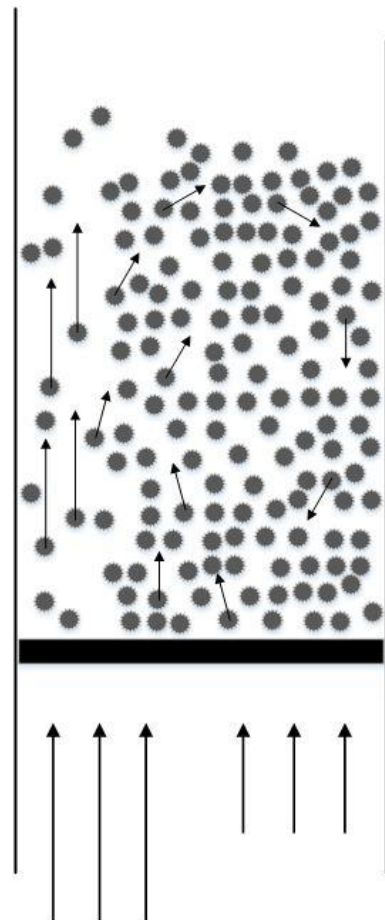


Figure 7. Channeling and gulf-streaming of fluidized bed.

Channeling is a strongly unwanted situation because the contact of the fluid with the solid particles decreases substantially. Channeling can also cause hotspots where exothermic reactions take place more than the rest of the bed.[16] Channeling may also cause termination of fluidization when the pressure drop decreases leading to the fluid velocity to drop below supporting levels for the particles in the other parts of the bed.[18]

Courderc and Angelino (1970) cited by Davidson et al. (page 7) states that channeling can be avoided by using a greater homogenization section and more efficient fluid distributor.[3] Zenz et al. wrote that channeling can be restrained by using a distributor plate that has a pressure drop of at least 40% through the fluidized bed.[16]

In equation 2, a channeling factor x_d is shown, which can be expressed by the difference between expected fluidized bed pressure drop that can be calculated with the equation 18 and pressure drop of channeled bed and the difference divided by the pressure drop of expected fluidized bed. Channeling factor can be used to compare the channeling behavior of different beds. The larger channeling factor implies greater channeling tendency.[18]

$$x_d = \frac{\Delta p_t - \Delta p_{cb}}{\Delta p_t} \quad 2$$

3.5.2 Gulf-streaming

When the fluidized bed is channeling, it causes phenomena called gulf streaming. In gulf streaming there is a distinct gross circulation flow pattern where the particles rise in one part of the column cross-section and in the other part- typically near the column walls- they are flowing downwards.[7,10,13,19,20] Near the top and the bottom of the fluidized bed these particle flows combine forming a circular flow pattern. In gulf streaming, the solid particles are conveyed more rapidly than in fluidization without channeling and gulf streaming.[3] Gulf streaming has been observed in both dispersed bubble and coalesced bubble regimes.[10]

The existence of the gross circulation flow pattern depends strongly on the superficial gas velocity.[10] At low superficial gas flow velocities the gulf-streaming cannot be clearly observed. In these velocities bubbles rise rectilinearly in the column. If the gas velocity is increased there is a point called critical gas velocity, where the bubbles near the walls of the column start to shift towards the center breaking the rectilinear pattern.[13] Gulf streaming can be a more important mechanism for mixing than the mixing caused by bubbles.[20]

3.6 Solids flow structure in gas-liquid-solid fluidized bed

Cassanello et al. formed a model that can be seen as a simplified structural wake model. The gas-liquid-solid fluidized bed is divided into three separate “phases” in order to study the hydrodynamics of the solid particles. These phases are bubble phase, wake phase and emulsion phase. Where the bubble phase is gas bubbles, free from solids and liquids, traveling upwards in the column. The wake phase consists of liquid and solids following bubbles moving upwards. The emulsion phase consists of liquid and solids traveling downwards in the column.[21]

In the model described by Cassanello et al., there were some generalizations. The movement of solids is only considered to be due to primary wakes and other mechanisms are neglected. Another assumption is that the wake is considered to be moving with the same velocity as the bubble. The third assumption is that there is continuous mass transfer of particles between the emulsion phase and the wake phase.[21]

Cassanello et al. found out that in the heterogeneous flow regime velocities of the solid particles accelerates near the bottom of the column. Afterwards, the velocities remained constant until they reach the disengagement zone in the upper parts of the bed, where the velocities decelerate.[21]

Cassanello et al. have also studied the chaotic behavior of the gas-liquid-solid fluidized bed. In their experiments, the Kolmogorov entropy, describing the required accuracy of the initial conditions in order to predict the system evolution was positive in both liquid-solid and gas-liquid-solid fluidization. This suggests that the fluidized bed was chaotic. The degree of chaoticity increases with increasing the superficial gas velocity.[22]

3.7 Forces affecting on the particles

There are three forces acting on the particles during the fluidization: gravitational force, buoyancy and drag forces. According the Newton's first law, when these forces are balanced, the particles are moving at constant velocity as shown in equation 3. From these the gravitational force is the only unambiguous force.[23]

$$F_k + F_s = F_g \quad 3$$

There are two ways by which buoyancy force in a fluidized bed is represented in the literature. One is called apparent buoyancy, and the other Archimedes buoyancy, $\bar{\rho}gv$ and $\rho_f gv$ respectively, where $\bar{\rho}$ is the suspension density and ρ_f is the density of the percolating fluid. Because the gravitational force is undisputed, the buoyancy dispute affects also the magnitude of drag force because the sum of forces are zero, if the particle is not accelerating.[24]

In laminar flow the Drag force affecting a single particle can be calculated with Stokes law shown in equation 4.[25]

$$F_{ks} = \frac{3\pi\mu V d_p}{g_c} \quad 4$$

Where μ is viscosity of fluid, V superficial velocity of fluid, d_p diameter of the sphere particle and g_c is conversion factor. To cover all the flow conditions with Reynolds number from 0.001 to 1000 equation 5 was formed.[25]

$$F_{ks} = \frac{\pi d_p^2 \rho_f V^2}{g_c} (3Re^{-1} + 0.45Re^{-0.313}) \quad 5$$

In the multiparticle system, the drag force acting on each particle is depending on the voidage of the system. In order to assess drag force of the bed F_k , the drag force ratio $f(\varepsilon)$ needs to be defined. It is the ratio between the drag force of the bed and a single particle, as shown in equation 6.[25]

$$f(\varepsilon) = \frac{F_k}{F_{ks}} \quad 6$$

The voidage indicates the “open” area of the columns cross-section that the solid particles are not filling. Voidage of the bed can be calculated with equation 7.[26]

$$\varepsilon = 1 - \varepsilon_s = \varepsilon_l + \varepsilon_g \quad 7$$

Wen and Yu found out that this relation can be presented as in equation 8.[25]

$$\frac{F_{ks}}{F_k} = \varepsilon^{4.7} \quad 8$$

Now the drag force of multi particle system equation 9 can be written.[25]

$$F_k = \frac{\pi d_p^2 \rho_f V^2}{\varepsilon^{4.7} g_c} (3Re^{-1} + 0.45Re^{-0.313}) \quad 9$$

3.8 Other fluidization characteristics

When the bed is fluidized it has distinctive characteristics like hold-ups and pressure drop. When the fluid is flowing through the bed it causes a pressure drop in the fluid. In the other hand, the hold-ups are proportional to the phases presented in the bed. Phase hold-ups and pressure drops of the bed are strongly related[1].

3.8.1 Hold-up

In fluidized bed the solid hold-up ε_s can be calculated with equation 10.[1,8]

$$\varepsilon_s = \frac{W}{\rho_s S H} \quad 10$$

Where W is weight of the solid particles in the bed, ρ_s is density of the solid, S is cross-section area of the column and H is effective height of the bed.[8] The bed height can typically be measured by visual observation, especially with larger and heavier particles.[1]

The sum of the gas, solid and liquid hold-ups is one, which is presented in the equation 11.[1,8]

$$\varepsilon_s + \varepsilon_l + \varepsilon_g = 1 \quad 11$$

In the steady-state, the static pressure gradient can be presented with equation 12.[1,8]

$$-\frac{dP}{dz} = (\varepsilon_s \rho_s + \varepsilon_l \rho_l + \varepsilon_g \rho_g)g \quad 12$$

In equation 12, the frictional drag on the column walls is neglected as well as gas and liquid acceleration terms.[1] The gas term is usually insignificant compared to other terms, so it is usually ignored, thus giving the equation 13.[1,8]

$$-\frac{dP}{dz} = (\varepsilon_s \rho_s + \varepsilon_l \rho_l)g \quad 13$$

The solid hold-up can be calculated directly from equation 10; the liquid hold-up can then be calculated from equation 13, provided that the static pressure gradient is measured simultaneously.[8] Liquid hold-up can also be evaluated with an electrical conductivity method.[1] Liquid hold-up can be estimated with dimensionless correlations rather accurately.[27]

For the gas hold-up it is challenging to develop any correlation that covers all the circumstances since the gas hold-up is strongly dependent on the flow regime.[1] Although Larachi et al. later wrote that gas hold-up is affected mainly by solid and gas inertial forces, it decreases when the liquid capillary and viscous forces are increased.[27]

Gas hold-up is possible to calculate by combining the equations 11 and 12 to the equation 14.

$$\varepsilon_g = \frac{\frac{dP}{dzg} + \varepsilon_s(\rho_s - \rho_l) + \rho_l}{\rho_l - \rho_g} \quad 14$$

When comparing the gas hold-up in bubble column and gas-liquid-solid fluidization, the gas hold-up varies noticeably. If the particles cause bubbles to coalesce, the gas hold-up can be lower. If the particles causes bubbles to break up, the gas hold-up might be higher.[1]

3.8.2 Pressure drop

In the ideal fluidized bed system, when superficial fluid velocity is increased from zero to the point of minimum fluidization velocity, the particles in the system generates pressure drop that increases with the fluid velocity.[3,6]

Pressure drop caused by the bed below the minimum fluidization velocities can be assessed as the pressure drop of packed bed. The factors causing the pressure drop in the packed beds are usually considered to be fluid flow rate, viscosity and density of the fluid, fractional void volume and orientation, size, shape as well as surface of the particles. With slow flow velocities the pressure drop is proportional to the flow velocities and for higher velocities the pressure drop is proportional approximately to the square of the velocity. The effect of density and viscosity to pressure drop can be seen in equation 15.[28]

$$\frac{\Delta p_t}{L} = a'\mu U + b\rho U^2 \quad 15$$

Where a' is a factor relating to the variables of the solids, μ is viscosity and ρ is density.

When the pressure drop generated by the bed is enough to support the particles throughout the bed, the bed is in fluidization, so that the particles are not supported by the distribution plate anymore.[5] While increasing the fluid flow velocity further the pressure drop will stay relatively constant, i.e. the increase in the fluid velocity will not have a significant difference in the pressure drop of the bed.[3,4]

For the flow velocities below the minimum fluidization velocities, pressure drop can be calculated with Ergun equation 16.[4]

$$-\frac{\Delta p_t}{L_{mf}} = f \frac{\rho_g (U_{mf}^s)^2}{d_p} \quad 16$$

Where f is a friction factor that can be calculated with equation 17.[4,28]

$$f = \frac{1 - \varepsilon}{\varepsilon} \left(1.75 + \frac{150(1 - \varepsilon)}{Re_p} \right) \quad 17$$

In the minimum fluidization velocities drag force and the weight of the average cross-section of bed are equal. From those we obtain equation 18.[4]

$$-\frac{\Delta p_t}{L_{mf}} = (1 - \varepsilon_{mf})(\rho_p - \rho_f)g \quad 18$$

Equations above are only suitable for fluid velocities at and below minimum fluidization velocity. In the ideal situation, the pressure drop will not increase from minimum fluidization velocity onwards.[3]

Superficial fluid velocity at minimum fluidization can be calculated by combining equations 16 and 18 the equation 19 is formed.

$$U_{mf}^s = \frac{d_p(1 - \varepsilon_{mf})(\rho_p - \rho_g)g}{\rho_g f} \quad 19$$

3.8.3 Bed expansion

When solid particles are fluidized with the liquid phase, the height of the bed increases with the increase in fluid flow.[14,29] When introducing the gas flow to the liquid-solid fluidized bed, the bed starts to contract slightly.[1,14,29,30] Increasing the gas flow increases the contraction until the point of critical gas flow, where the bed starts to expand. The grade of contraction is even greater with higher liquid velocities.[1]

The expansion and contraction of the fluidized bed can be explained with wake models. In the wake model the fluidized bed can be divided into three regions: gas bubble region, a wake region, and a liquid-solid fluidized region. The sum of these volume fractions is one. This model also requires a few assumptions. Firstly, in the wake, the solid content can be an arbitrary value differing from the liquid-solid region. Secondly, the wake behind the bubble raises at the same velocity as the bubble.[1] Thirdly, the Richardson-Zaki correlation between solids hold-up and liquid velocity is applicable in liquid-solids region.[1,31]

3.9 Other factors affecting on fluidization

Others factors affecting on the fluidization behavior are, the distribution plate, all the solid particle properties, and the effect of the column wall. The distribution plate is an important factor regarding the hydrodynamics of the fluidized bed[26]. For example, even the small unevenness on the distribution of the fluids affect greatly on the velocity profile of the flow and, thus, on the fluidization behavior. Solid particle properties like shape, size, density and surface properties are also important factors affecting the fluidization. In addition, the column walls also affects

to the fluidization, however the effect is normally considered diminishingly small, so it is usually ignored[32]. Effect of distributor and particle properties are covered more closely.

3.9.1 Distributor

The distribution plate's task is to prevent solids from dropping out of the fluidized bed and to distribute the fluid flow evenly across the bed.[7,33] The distribution plate generates a pressure difference for the flowing fluid and generally the greater pressure difference the distribution plate generates, the more uniform flow it generates above the plate. However, the greater pressure drop will also cause the pumping of the fluid to be more expensive. Optimally the pressure drop would be just enough to ensure the uniform flow velocity distribution.[7]

The fluid flow resistance in the fluidized bed does not change substantially with increase in fluid flow. However, in the distribution plate, the resistance increases with the increase in the fluid flow. Indicating that the increase in pressure drop in the distribution plate has an effect on the fluidization characteristics.[26]

The pressure drop caused by the distribution plate is usually compared with the pressure drop caused by the bed. There are multiple different recommended ratios for the ratio between the pressure drop caused by the distribution plate and the pressure drop caused by the bed.[7,26] In literature, distribution plates can generate pressure drop ratios normally varying from 0.015 to 0.4 but even higher ratios can also be used. The distribution plates have been categorized in low pressure drop and high pressure drop classes. If the pressure drop ratio is between 0.015 and 0.2 it is considered to be a low pressure drop plate; if the pressure drop ratio is more than 0.4, it is considered as a high pressure drop distribution plate.[26]

The required pressure drop ratio for uniform fluidization depends moderately on the solid particle size. Siegel wrote that particles with roughly a diameter of 0.5 mm would require pressure drop ratios greater than 0.25, whereas particles with diameter of 23 μm would only need approximately 0.15 pressure drop ratio.[34] The needed pressure drop ratio for uniform fluidization also depends on the fluid superficial flow velocity. Shi and Fan wrote that if the fluid superficial flow velocity

is 1.5 times the minimum fluidization velocity, the pressure drop ratio should be 0.11 with perforated distributor and 0.18 with porous distributor. While the fluid velocity increases, the needed pressure drop ratio increases also.[33]

3.9.2 Particle shape, size and surface properties

The most important properties of the particles are size, density and flowability. [20] In addition, roughness and voidage associated with particles should also be considered.[26]

Defining the size of the particle is rather straightforward with spherical particles. Only the diameter of the spherical particle is required for defining the size. For other particles the size can be defined by measuring the volume of the particle and then defining the diameter of the equivalent volume sphere. There is a parameter called sphericity ϕ_s shown in equation 20.[7]

$$\phi_s = \frac{A_{sph}}{A_{part}} \quad 20$$

Where the sphere and particle are the same volume and the A_{sph} is the surface area of the equivalent sphere and A_{part} is surface area of the particle.

The solid particles in the system are usually considered spherical when assessing the behavior of the particles. Frequently this is not the case, however it is still important to know how the properties of the particles change with different shapes. For assessing non-spherical particle properties, there are multiple correlations.[1,3]

Roughness of the particles adds friction between the particles causing the increase in bed porosity. In consequence, the pressure drop of the bed will be higher with rough particles compared to bed with smooth particles. The roughness of the particle can be assessed by measuring the friction factor of the particles.[26]

3.10 Particulate and aggregative systems

In the fluidized bed, there are two states concerning how the particles are distributed during fluidization. These states are called particulate and aggregative. In the particulate system, the fluidized particles are distributed uniformly. In aggregative systems particles are distributed unevenly, which indicates that in some parts of the fluidized bed the particles are distributed more densely, and in other parts sparser. Particulate systems are usually associated with liquid-solid fluidization, whereas aggregative systems are associated with gas-solid fluidization.[3]

However, the distinction between particulate and aggregative system is not that simple. In addition to liquid-solid fluidization, the particulate behavior can be observed also with gas-solid system, when the solid particles are light.[3] Aggregate behavior can be observed additionally with water and very dense particles[35], such as copper and lead particles[2,35]. There are not yet any definite criteria is that applicable under all conditions for defining if the fluidization will behave as particulate or aggregate system.[35,36]

There are a few methods that helps in distinguishing if the fluidization is aggregative or particulate. The Froude number explains the quality of the fluidization.[2,17] The local heterogeneity index describes the local characteristics of the intermediate states and the global nonideality index describes the bed expansion characteristics. The discrimination number describes the transition between particulate and aggregative fluidization.[37]

3.10.1 Froude number

Wilhelm and Kwauk wrote that Froude number provides a suggestive figure that tells if the fluidization in minimum fluidization is particulate or aggregative. The equation for Froude number is presented in equation 21. If the Froude number is less than 0.13, fluidization is particulate; if the number is more than 1.3, the fluidization is aggregative.[2]

$$Fr = \frac{U_{mf}^2}{gd_p}$$

21

3.10.2 Local heterogeneity index

Local heterogeneity index δ is a relative measure that describes the local characteristics of the system voidages.[37] This method is valid only in two-phase fluidization. The index varies between 0 and 1, where 0 is fully homogenous fluidization and 1 is the most heterogeneous fluidization i.e. slugging[37].

The samples of the fluctuating voidage signal obtained by optical fiber probe is required for first calculating the standard deviation of voidages. The standard deviation can be calculated with equation 22.[36,37]

$$\sigma = \sqrt{\frac{1}{n} \sum_{i=1}^n (\varepsilon_i - \varepsilon)^2}$$

22

Where n is the number of samples measured with the probe. As a result different σ values describes the different configurations of phase mixtures. Taking into account the slugging as the most heterogeneous pattern and that the signal detected by the probes varies between ε_{mf} and 1. Where ε_{mf} illustrates the voidage in dense phase at minimum fluidization and 1 the bubble phase. Thus, with samples n_1 and n_2 , equations 23, 24 and 25 are obtained.[37]

$$n = n_1 + n_2$$

23

$$\varepsilon_i = \varepsilon_{mf} \quad (i = 1 \rightarrow n_1) \quad 24$$

$$\varepsilon_i = 1 \quad (i = 1 \rightarrow n_2) \quad 25$$

Then by combining the equations 22, 23, 24 and 25 we get equation 26 for standard deviation for slugging, and by deriving that we get equation 27.[37]

$$\sigma_{slugging} = \sqrt{\frac{1}{n} \left(\sum_{i=1}^{n_1} (\varepsilon_{mf} - \varepsilon)^2 + \sum_{i=1}^{n_2} (1 - \varepsilon)^2 \right)} \quad 26$$

$$\sigma_{slugging} = \sqrt{\frac{1}{n} (n_1 (\varepsilon_{mf} - \varepsilon)^2 + n_2 (1 - \varepsilon)^2)} \quad 27$$

For slugging, the volume fraction of dense phase is f , so we obtain equations 28 and 29.[37]

$$f = \frac{n_1}{n} \quad 28$$

$$1 - f = \frac{n_2}{n} \quad 29$$

In continuation, by combining equations 27, 28 and 29 we get equation 30.[37]

$$\sigma_{slugging} = \sqrt{f(\varepsilon_{mf} - \varepsilon)^2 + (1-f)(1-\varepsilon)^2} \quad 30$$

From that, when the definition of average voidage is expressed in equation 31, we acquire the equation 32 from equations 30 and 31.[37]

$$\varepsilon = f\varepsilon_{mf} + (1-f) \quad 31$$

$$\sigma_{slugging} = \sqrt{f(1-f)}(1-\varepsilon_{mf}) \quad 32$$

The maximum standard deviation can be found by differentiating the equation 32 with respect to f and then setting the derivative to 0.[37]

$$\frac{d\sigma_{slugging}}{df} = \frac{1-2f}{2\sqrt{f(1-f)}}(1-\varepsilon_{mf}) = 0 \quad 33$$

Which derives $f=1/2$ and by substituting it to equation 32, equation 34 is formed.[37]

$$\sigma_{max} = \frac{1 - \varepsilon_{mf}}{2} \quad 34$$

And then for any voidage sample with standard deviation, the heterogeneity index can be defined as in equation 35.[37]

$$\delta(u) = \frac{\sigma}{\sigma_{max}} = \frac{2\sigma}{1 - \varepsilon_{mf}} \quad 35$$

Because the standard deviation changes with velocity U , the heterogeneity index can also be obtained by integrating between minimum fluidization velocity and maximum velocity, thus, creating the velocity-averaged heterogeneity index presented in equation 36.[37]

$$\delta(u) = \frac{\int_{U_{mf}}^{U_{max}} \delta dU}{U_{max} - U_{mf}} \quad 36$$

For liquid-solid fluidization, the heterogeneity index number is relatively low and remains rather constant at all flow velocities[37], which states that liquid-solid fluidization is usually relatively homogenous and particulate in nature.

3.10.3 Global nonideality index

Global nonideality index f_h describes the difference between real and ideal expansion of the bed. In the ideal expansion there is a linear relationship among the logarithmic voidage and logarithmic superficial fluid flow velocity. In the ideal

case, the area A_P below the voidage-velocity expansion curve can be calculated with equation 37.[36,37]

$$A_P = \int_{U_{mf}}^{U_t} \varepsilon dU \quad 37$$

When $U=U_t\varepsilon^n$ we get the equation 38.[36]

$$A_P = \int_{U_{mf}}^{U_t} \varepsilon d(U_t\varepsilon^n) \quad 38$$

And when integrating equation 38 we acquire equation 39.[36]

$$A_P = \frac{n}{n+1} U_t (1 - \varepsilon_{mf}^{n+1}) \quad 39$$

For any real fluidized beds, the corresponding area is calculated with equation 40.[36]

$$A_R = \int_{U_{mf}}^{U_t} \varepsilon dU \quad 40$$

A_P is generally greater than A_R indicating that the real expansion is usually less than in ideal cases. The global nonideality index f_h is calculated with equation 41

and it illustrates the difference in the area of the real situation and the ideal situation. Equation 41 is also represents the differential area under the voidage-velocity curves. Nonideality index is equal to 0 when the bed is expanding ideally. When nonideality index is greater than 0 which indicates that the bed is nonideal. The greater the nonideality index is, the more nonideal the bed expansion is.[36]

$$f_h = \frac{A_P + A_R}{A_P} = 1 - \frac{A_R}{A_P} = 1 - \frac{(n+1) \int_{U_{mf}}^{U_t} \varepsilon dU}{nU_t(1 - \varepsilon_{mf}^{n+1})} \quad 41$$

3.10.4 Discrimination number

When defining the fluidization pattern, the most important factors are particle size, particle density, fluid density, and fluid viscosity. Dimensionless discrimination number D_n combines all of these properties. The lower the discrimination number is, the more uniform the fluidization will be.[37]

$$D_n = \left(\frac{Ar}{Re_{mf}} \right) \left(\frac{\rho_p - \rho_f}{\rho_f} \right) \quad 42$$

Where the first bracketed equation represents the effect of particle size and the fluid viscosity and effect of densities are represented in the second. Re is Reynolds number and Ar is Archimedes number, which can be calculated with equations 43 and 44, respectively.

$$Re = \frac{d_p U \rho_f}{\mu} \quad 43$$

$$Ar = \frac{d_p^3 \rho_f g (\rho_p - \rho_f)}{\mu^2} \quad 44$$

According to Wen and Yu a correlation between Reynolds number as a function of Archimedes number can be represented as equation 45. A ratio for Archimedes number and Reynolds number can be obtained through equation 46.[38]

$$Re_{mf} = \sqrt{33.7^2 + 0.0408 Ar} - 33.7 \quad 45$$

$$\frac{Ar}{Re_{mf}} = 1652.0 + 24.5 Re_{mf} \quad 46$$

Liu et al. stated that the local heterogeneity index, global nonideality index and discrimination number change with similar trends. For particulate fluidization the discrimination number is between 0 and 10^4 , the global nonideality index is less than 0.2, and the local heterogeneity index is less than 0.1. On the contrary, for aggregative fluidization the discrimination number is more than 10^6 , global nonideality index is more than 0.6, and the local heterogeneity index is more than 0.5. For everything in between, the fluidization is at a transitional state.[37]

4 Fluidization processes in practice

Gas-liquid-solid and liquid-solid fluidization processes has been and are still vastly used in industries such as chemical, petroleum, environmental, metallurgical and energy industries.[3] A few of these processes are described more throughout in following chapters.

4.1 Gas-liquid-solid fluidization processes

In gas-liquid-solid fluidization the different phases can be reactants, catalysts, products or inert. In the same system all the phases can be, for example, reactants or products like in coal liquefaction. Alternatively, in the same system, the gas and liquid phases can be reactants and products when the solid is catalyst as in hydrogenation. If there is an inert phase it can also be in any of the phases. Three phase fluidization is used also in systems without reactions as in air humidification.[1]

In addition to hydrotreating, the gas-liquid-solid fluidization is used for example in bioreactors, wastewater treatment, flue gas treatment, and in other systems.[1]

One of the most important application of the gas-liquid-solid fluidized bed is hydrotreating in the petroleum industry. The feedstock can be for example heavy oil, petroleum resin or synthetic crudes from coal and tar sands. Reactions in the hydrotreating processes are for example cracking, hydrocracking, hydrodesulfurization, hydrodeoxygenation, hydrodenitrogenation, and hydrodemetallization. Feedstock is fed to the reactor in liquid phase. In the gas phase there is hydrogen and the solids are catalysts. In the reactor the temperature is usually from 300 to 425 °C and the pressure is from 5.5 to 21 MPa.[1]

In bioreactors, the solid phase in fluidization is usually composed of immobilized cells. The solid particles are made by attaching cells to particles, so that they will grow into biofilm to the surface of the particles. In the bioreactors the liquid input is usually so minor that the particles are fluidized with gas flow. The composition of the gas phase depends on whether the reaction is aerobic or anaerobic. For aerobic reactions, the gas flow is usually air or oxygen. Whereas in anaerobic reactions the gas phase used is inert such as nitrogen. These kind of processes are used for example in production of ethanol, glutathione, amino acids, antibiotics and enzymes.[1]

Fluidized bed is used also in aerobic biological wastewater treatment. In this system the microbes are attached to the surface of the solid particles. The microbes removes organic and inorganic compounds from the wastewater. Gas phase fed to the reactor is oxygen or air and the liquid phase is the wastewater to

be treated. Advantages of the fluidized bed reactor can be found through a comparison against traditional bioreactors. For instance microbe washout is lower and the system does not clog easily.[1]

The flue gases of heavy oil and coal combustion, smelting processes, sulfuric acid manufacture and metallurgical processes contain unwanted sulfur dioxide and particulates. A suitable process for removing these unwanted substances is wet scrubbing. This process includes usually a gas-liquid-solid fluidized bed. In the process the flue gas is fed to the fluidized bed as a gas phase and then soluble sulfite is fed to the reactor to absorb the SO_2 . The solid phase is present as calcium oxide in the reactor, which reacts with SO_2 to form CaSO_3 that is then removed with the liquid-solid separator outside of the column.[1]

4.2 Liquid-solid fluidization processes

Liquid-solid fluidization is not as frequently used as gas-liquid-solid fluidization, however liquid-solid fluidization still has a great variety of different applications. Liquid-solid fluidization is used, for example, in separating particles by size and density, backwashing of granular filters and washing of soils, crystal growing, adsorption as well as ion exchange, electrolysis and bioreactors[39].

Bioreactors are also a much used application for liquid-solid fluidization especially in wastewater treatment. Solid phase in fluidization is coated similarly with microbes as in the gas-liquid-solid aerobic biological wastewater treatment. The difference is that the wastewater is oxygenated prior to feeding it to the system.[1]

5 Mixing of solid particles

Understanding the solids mixing is an important part of the design of the fluidized bed reactor.[40] In reactors, it is essential to achieve comprehensive mixing to assure uniform particle distribution and to avoid possible hotspots. Poor mixing also lowers the efficiency of the reactions. Therefore, it is crucial to understand the particle mixing behavior to assure the most efficient reactions.[41]

Near the minimum fluidization the mixing of the solid particles are relatively slow. Particles only shake staying in rather constant place and, occasionally, some of the particles change position with other particles nearby. The particle mixing in conditions under the minimum fluidization resembles diffusion, where the mass transfer is rather slow compared to the convection. There are two significant mixing mechanisms, one is due to the bubble movement and the other is due to uneven distribution of the fluid.[20]

The mixing induced by bubbles occurs when the solids close enough to the rising bubbles are drawn into the wake of the bubble where complete mixing of solids occurs. This causes - partially - the lateral mixing of particles, and more significantly, the vertical mixing due to the wake moving up. The wake fragments are replenished with particles as the bubble move by. When the bubble reaches the surface of the bed, the eruption of the bubble causes part of the particles in the wake to spread within the wide area and the rest are thrown into the freeboard region from where they descend back to the surface of the bed.[20,40]

Predicted mixing times, obtained from the simulation model of Cassanello et al. taking into account the wake mode, were systematically longer than experimentally obtained mixing times. Implying that the bubble wake phenomena by itself is not enough to explain mixing of the solids. Other mechanisms like drift effect, diffusion-like solids dispersion and radial convection velocities needs to be taken into account.[21]

Mixing can be assessed by following the movement and location of the tracer particles in real-time or by examining the mixing result subsequent to the experiments.[42] The residence time distribution can be created while obtaining the real-time tracer location data; this shows in which parts of the column tracer particles have been located.

Subsequent to mixing, the degree of mixing can be quantified, for example, with the mixing index or the mixing time. The mixing index describes how well mixed the mixing samples are. Whereas mixing time is used to assess the time in which the system needs to accomplish the complete mixing.

5.1 Mixing index

The mixing index is used to characterize the degree of mixing. In this method the amount of the tracer particles are evaluated in a sample. The tracer particle concentrations are described with two parameters: the ratio between the number of tracer particles in sample and the number of tracer particles in whole bed, presented in equation 47, and the concentration of the tracer particles in sample, presented in equation 48.[43]

$$c = \frac{n_i}{n_t} \quad 47$$

$$c_{li} = \frac{n_i}{n_{it}} \quad 48$$

Where n_i is number of tracer particles in sample, n_t number of tracer particles in the whole bed and n_{it} is number of particles in the sample. The mixing index M is presented in equation 49.[43]

$$M = \frac{\sigma(c_{li})}{\bar{c}} \quad 49$$

Where $\sigma(c_{li})$ is standard deviation as a function of the concentration of local tracer particle. It can be calculated with equation 50. And \bar{c} is the average concentration of tracer particles in the whole bed.[43]

$$\sigma(c_{li}) = \sqrt{\frac{\sum_{i=1}^m (c_{li} - \bar{c})^2}{m}} \quad 50$$

Where m is the number of sampling cells in the system.[43] When M is equal to zero, the system is completely mixed, indicating that in the samples the

concentration of the tracer particles is equal to the concentration of the tracer particles in the whole system. The sample size must be large enough so that the random errors will not affect the concentration calculations[44].

5.2 Mixing time

The time that is required to accomplish the complete mixing is called mixing time. Euzen and Fortin, cited by Fan[1], wrote that the mixing time decreases when the gas velocity is increasing. In addition, the rate of the decrease was significantly higher for low liquid velocity than high liquid velocities.[1] In other words, the complete mixing would be accomplished more quickly with higher gas velocities and low liquid velocities.

6 Particle movement tracking

When assessing particle movement, there are invasive and non-invasive measuring techniques. The invasive techniques are usually different kind of probes that have been inserted in the flow region, which interferes with the flow and hydrodynamics that could possibly lead to changes in the behavior of the system. Invasive techniques are used more in the full scale industrial factories, because the non-invasive measurement used in laboratory scale might not be sufficient for running measurements deep in large industrial systems. In addition, the invasive technologies are usually easier to apply and are often cheaper. Non-invasive measuring techniques do not interfere with the system at all.[45]

When using the tracer particles in fluidization, it is important that properties of the particles such as density, size, shape and surface properties to be nearly identical with the other particles in the bed. In this way, the tracer particles would represent all the other particles well.

Often the solid flow velocities and solid patterns are measured by observing the movements of solid tracking particles. This method usually does not distinguish single particles, but follow the particles as a mass. Nonetheless, it is usually more useful to know how a single particle is moving and its residence time in different parts of column.[46] The method where all the particles in the bed are tracked is

called tomography, while the tracking of single particle is simply called single particle tracking.

Particles that are tracked are usually radioactive or optically detectable. Radioactive particle tracking methods include positron emission particle tracking (PEPT) and radioactive particle tracking (RPT), which is based on tracking gamma-rays. Whereas, optically detectable particles can be tracked with analyzing videos or photos, laser Doppler anemometry (LDA), particle image velocimetry (PIV), and fluorescent particle image velocimetry (FPIV).[47] In addition to those mentioned above, particle movement can be observed for example by following the movement of ferromagnetic substances or particles with radio frequency identification tags (RFID).

The optical tracking methods are usually used with refractive index matching techniques. These techniques are used, for example, in laser Doppler velocimetry, particle image velocimetry and photographic techniques. Refractive index matching means that the refractive index of the column walls, the liquid and the particles in bed are similarly matched. This enables the observation of the systems without refraction errors.[48]

6.1 Positron emission particle tracking

In positron emission particle tracking (PEPT), the particle tracking is carried out by following the gamma rays to locate the solid tracer particles containing positron emitting substance. These tracers emits positron, which quickly annihilates with electron to form two collinear gamma rays. These rays can be observed with detectors outside the column. As the path of the rays are collinear, we can calculate the line on which the particle is located. When another positron is emitted, another line can be calculated and from those the location of the particle can be triangulated. As the particle keeps emitting positrons as it moves by, the location of the particle can be tracked.[46]

6.2 Radioactive particle tracking

One used method for tracking a single particle in fluidization is radioactive particle tracking method (RPT). In this method a non-invasive single radioactive particle is

fed into the fluidized bed and then the emitted radiation is measured[12] for long periods of time such as 8-12 hours.[49] This method is found to be a very reliable techniques for investigating the movement of solid particles. Radioactive particle tracking method can be utilized, for example, for quantification of the solid flow structure, to obtain the solid flow velocity distributions, for evaluating the solids mixing in the three-dimensional space and for mapping the solid velocity vectors.[12]

Larachi et al. utilized the RPT system with eight NaI(Tl) detectors to measure the emitted γ -rays in their studies. The data from all eight detectors were collected and used for mapping the three-dimensional location of the particle. To be able to gain useful location data from the detectors, the system needs to be calibrated every time prior to measurements. This is done by positioning the particle in known locations of the column.[12,49]

The tracer used in Larachi et al. experiments was a mixture of soda lime powder and scandium oxide, which was melted at high temperature. The density of the formed particle was rather close to the density of the glass particles used in the fluidization experiments. The particle was then activated in a nuclear reactor. ^{46}Sc emits γ -rays with energies of 889 and 1120 keV and the half-life of ^{46}Sc is 83.8 days.[49]

6.3 Imaging techniques

Different kinds of imaging techniques are usually used in observing and analyzing the particle movements.[19,30,43,50] The imaging techniques has developed greatly in recent years. When previously the cameras took a few picture per seconds, nowadays cameras can take thousands of digital pictures per second with great definition. This enables the image processing and obtaining of data with different tools from the pictures to be considerably easier.

Imaging techniques requires a see-through column and can be used with the refractive index matching techniques. Imaging techniques also requires an external light source, so that the image sensor gets enough exposure. However, the imaging is usually limited just to the particles in the vicinity of the walls[46].

6.4 Particle image velocimetry

Particle image velocimetry (PIV) is a technique that follows the particle movement by taking pictures of the system. Lasers can be used as sources of light. PIV is also used to examine the flow structure of gas or liquid with the help of seeding particles[45].

PIV equipment normally includes four basic parts. The PIV measurements are based on recording optically the movement of particles, so the first equipment required for PIV is a recording device, normally a camera that takes pictures of the system. A commonly used camera is the CCD camera. Other cameras include cameras film or holographic cameras. Because in PIV the particles are followed optically, the column has to be transparent in order for camera to be able to see the particles in the column. The third piece of equipment needed is a light source, so that the particles are illuminated enough for the camera. A frequently used light source is the laser, the beam of which is reflected to form a pulsing “sheet” of light, although, for larger particles, less powerful light source might be enough. The final part of the PIV equipment needed is the image processing equipment, so that the movement data can be extracted from the pictures.[51,52]

The tracer particles used in PIV needs to stand out optically from other particles in the system. This can be accomplished for example by painting the tracer particles with different colors so that the contrast difference would separate tracer particles from the rest. Painting the tracer particle with fluorescent paint - so that the tracer particle would emit light that can be identified – is another method in which to highlight the tracer particles. Ideally the particles that are not been tracked would be transparent so that they will not hinder the visibility of the tracer particles. Even so, the problem with transparent particles might be that they refract the light, which can disturb the tracer particle tracking to some extent.

Nowadays it is more common and more practical to use digital imaging instead of the film photographic methods. Advantages of digital imaging include that the image can be processed immediately, so that the feedback of the images can be obtained immediately, and digital imaging has almost zero operating costs. Some photographic film devices are still used due to high spatial resolution. Digital imaging cameras commonly used in PIV are charge coupled devices (CCD),

charge injection devices (CID) or CMOS devices from which the CCD is the most used.[52]

6.5 Three-dimensional particle tracking velocimetry

In studies done by Shirsat et al., three-dimensional particle tracking velocimetry method were used. There, three high speed cameras recording the system simultaneously. Images from the three camera were then processed and the three-dimensional location of the particles obtained. In the Shirsat et al. experiments they tracked 400 particles simultaneously. However, with different particle densities, the amount could be greatly increased.[53]

6.6 Multiple color tracers

Mixing of solid particles can be observed by using multiple different color particles. Different color particles are set to the column layer by layer so that in one layer there are same color particles. This method gives information on how the particles have been mixed from the starting point. Drawback from this method is that data regarding the mixing is challenging to obtain during the mixing. Boyer et al.[45]:p3190 states that this kind of method was used in Fortin's experiments.

Zhang et al. used multiple color tracers with two different color particles. The different colored particles were set in in two layer. The first layer was 9 cm high and, above that, another 1 cm high layer of different color particles were set. Then the fluid flow to the bed was started. In a certain time the flashboard box was instantaneously inserted to the bed from the top. The box divided the bed into radial sections. The fluid flow was simultaneously shut down. Afterwards that the number of the tracer particles in different sectors were counted.[43] With this method it is was possible to see how the particles are distributed radially in the column.

6.7 Magnetic particle tracking

A rather new method for tracking solid particles is magnetic particle tracking (MPT). In this method single magnetic particle is tracked with multiple sensors, which measure the magnetic field generated by magnetic particles. The signals produced are used to calculate the particle location.[54]

An advantage of this method compared to radioactive tracers (PEPT and RPT) is the low cost since in PEPT and RPT the cost of the sensors and the cost of handling, preparing as well as using the radioactive material is considerably high. Furthermore, the safety issues due malhandling radioactive material cannot be overlooked. When comparing to magnetic particle tracking to imaging methods the advantage of magnetic particle tracking is that it is more easily adaptable to three dimensional systems.[54]

Avidan and Yerushalmi utilized the magnetic tracer tracking in their experiments. They injected magnetic tracer particles into fluidized bed, so that from all the bed particles 0.5% were tracers. The tracers were observed with four external probes that gave impulses that were translated to tracer concentration in the cross-section of the column.[55]

6.8 Thermal tracer tracking

Valenzuela and Glicksman used heated tracer particles that were tracked with multiple thermocouples. In this method, the particles were heated prior to inserting them into the bed. Particles are cooled down in minutes subsequent to insertion, so the experiments had to be repeated many times in order to obtain comprehensive data.[56]

Glicksman et al. used similar method but with cooled particles. Tracer particles were cooled to temperatures 100 degrees below the bed temperature with liquid nitrogen. After the particles had cooled down they were inserted into the bed. The particles were then traced with thermistors mounted on within the column. The particles were monitored 10 seconds subsequent to the insertion and because the particles were identical to bed particles there was no need to separate the tracers afterwards. Because of the short experiment times, the experiments must be repeated.[57]

Zhang et al. developed a technique that uses an infrared camera to track particles while the tracer particles are heated simultaneously with microwaves. The tracer particles were made of silicon carbide. Particles were observed with infrared video-camera through infrared permeable glass combined with a microwave blocking shield. The video was then processed and the particle movement data obtained

with computers.[41] This method is not suitable for systems containing polarized material like water.

Experimental part

7 Experimental setup

The column used in experiments is made of see-through Plexiglas and its height is 1.7 meter of which 1.2 meter is above the distribution plate. Cross-sectional shape of the column is square with internal dimensions of 0.1 m * 0.1 m. The distribution plate is perforated plate having 5 mm diameter holes with open area of 35 % and above the plate there is a small wire mesh. Column has Bürkert 8314 pressure transmitters with 25 cm intervals throughout the height of the column.

In addition to the column, the experiment equipment consists three subsystems, liquid feed, air feed, and data acquisition system. The liquid feed system includes liquid tank, pump and flow meter. The liquid tank is 300 liter in size with two inlet pipes near the top of the tank and one outlet pipe to the pump in the bottom of the tank. The tank has opening hatch on the top. The pump used is Ebara 3LM4 centrifugal pump. The flow velocity to the column is adjusted with two valves subsequent to the pump. One of the valves regulates the feed to the column and the second valve regulates the minimum circulation flow of the pump. Between the liquid feed valve and the column there is a liquid flow meter measuring the flow going to column. Liquid is fed through the flowmeter to the column from the bottom. The schematic diagram of the column is presented in Figure 8.

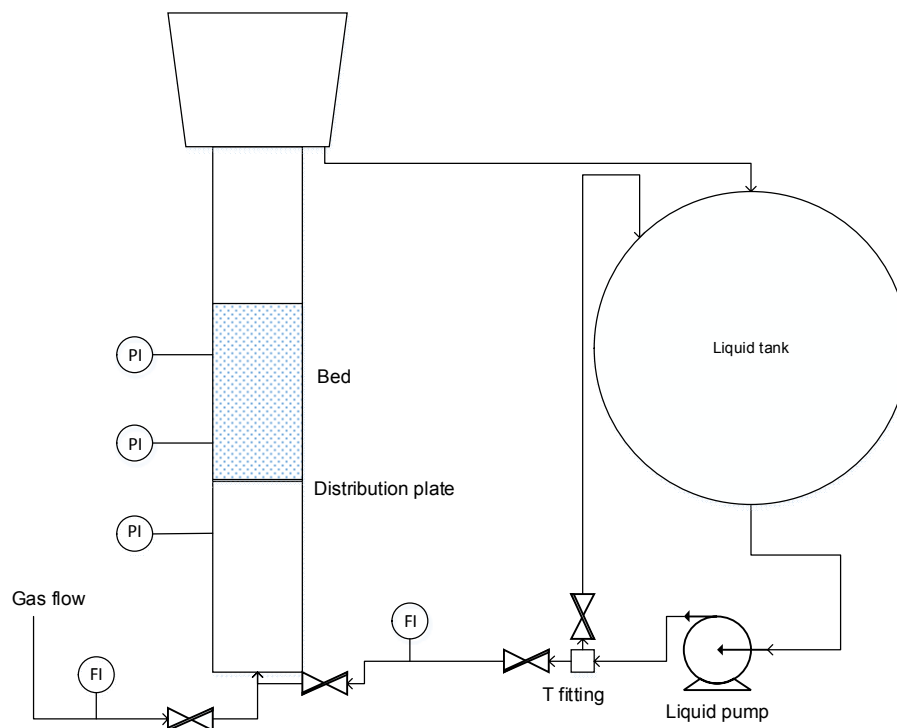


Figure 8. Schematic diagram of the experiment system.

The gas feed to the column comes from 5 bar pressurized air tap. From the tap the air is led through a hose and a ball valve to the CS Instruments VA 420 flow meter. Subsequent to the flow meter there is a no-return valve which prohibits the water from entering the air line. After the non-return valve there is another ball valve that can be also used to regulate the air flow to the column. The air is fed to the column also at the bottom of the column through nozzle.

Signals from pressure transmitters and flow meters are sent to Keysight/Agilent 34972A LXI Data Acquisition device with two Keysight 34901A modules. Data is logged with help of BenchLink Data Logger 3 software. Data logger is set to log measurements in 400 ms intervals.

The height of the bed and the movement of the particles were observed visually and recorded with Panasonic DMC-FZ1000 camera.

8 Operation principle

Objective of the experiments is to observe behavior and behavior changes with different gas flow and liquid flow rates. The experiments are carried out by adjusting flows with adjustable valves meanwhile pressure data in the column and flow velocity data are logged. In addition, particles, bubble and flow behaviors are observed both visually and recorded with camera.

9 Used materials

In the fluidization column there are gas, liquid and solid phases present. In these experiments the gas phase is pressurized air, liquid phase is tap water and solid particles are glass beads.

9.1 Solid particles

In the bed there are 6439.6 g SiLibeads glass particles with diameters varying from 2.0 to 2.5 mm. Less than 0.5 % of the particles are painted red, in order to ease the observing of the movement of the particles. The particles are all assumed to be spheres. The average wet density of the particles is 2471.1 g/l.

The tracer beads were painted with red spray-paint. The beads were set evenly on a flat surface and then spray-paint was applied evenly. When the particles had dried they were mixed and the painting procedure was repeated a few times in order to assure that all the sides of the beads were painted. Then the painted beads were let to dry for five days. The used spray-paint was Maston 805 RAL 3000 Red.

Mass of a single particle was determined by weighting 100 particles and assuming that they were representing all the particles in the bed. Average weight of one particle was 0.01505 grams, so that in one kilogram there are 66 450 particles. When the mass of the particles in the bed is known we can calculate that there are 427 900 beads in the bed.

Particle size was analyzed by measuring the particle diameter with Vernier caliper. Average diameter for 100 measured particles was 2.27 mm with standard deviation

of 0.108 mm. The particle size distribution is presented in Figure 9. All the particles were not exactly spherical however close enough to assume them to be.

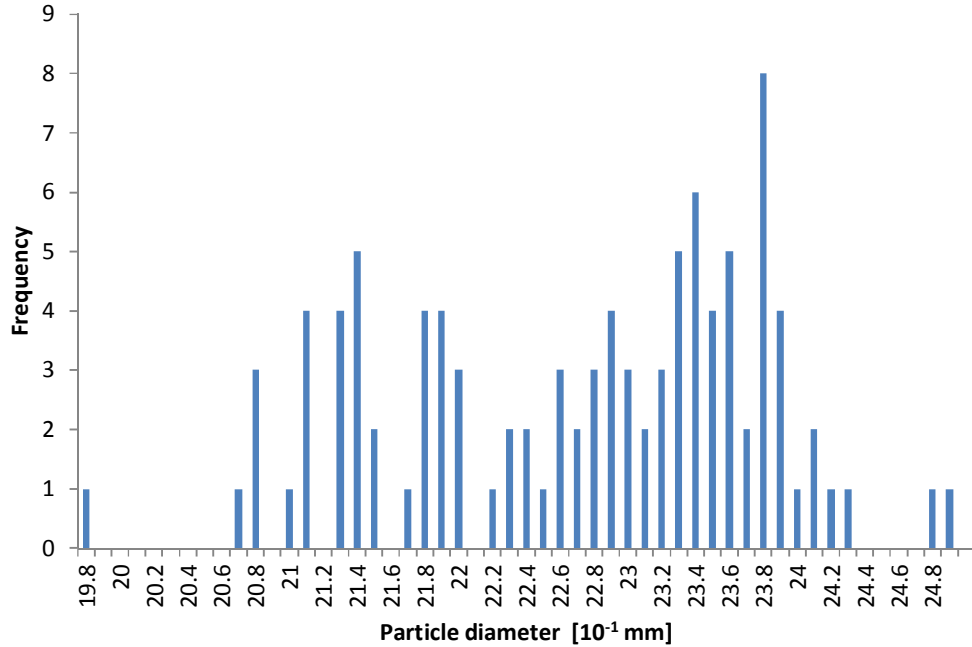


Figure 9. Particle diameter distribution.

The skeletal density of the particles were measured by a 250 ml volumetric flask. The empty volumetric flask was first weighed. Then to the flask was added certain amount of beads and then flask was weighed again. After that the volumetric flask was filled with 20 °C water until the 250 ml mark in the flask and then once again the flask was weighed. Then the skeletal density of the particles were calculated from the weight and the volume of the particles. Skeletal densities were defined with three different measurements for colorless beads and once with red particles.

$$\begin{aligned}
 m_{beads} &= m_{flask,beads} - m_{flask} = 364.13 \text{ g} - 92.76 \text{ g} \\
 &= 271.37 \text{ g}
 \end{aligned}$$

$$\begin{aligned}
m_{water} &= m_{flask,beads,water} - m_{flask,beads} \\
&= 504.96 \text{ g} - 364.13 \text{ g} = 140.83 \text{ g}
\end{aligned}$$

$$V_{water} = \frac{m_{water}}{\rho_{water}} = \frac{126.10 \text{ g}}{998.23 \text{ g/l}} = 0.141 \text{ l}$$

$$V_{beads} = V_{flask} - V_{water} = 0.250 \text{ l} - 0.141 \text{ l} = 0.109 \text{ l}$$

$$\rho_{beads} = \frac{m_{beads}}{V_{beads}} = \frac{271.37 \text{ g}}{0.109 \text{ g}} = 2491.52 \text{ g/l}$$

Table 1. Measurements for density of the beads.

	Mass of flask [g]	Mass of flask and beads [g]	Mass of flask, beads and water [g]	Mass of beads [g]	Mass of water [g]	Volume of water [l]	Volume of beads [l]	Skeletal density of beads [g/l]
batch 1	92.76	364.13	504.96	271.37	140.83	0.141	0.109	2491.52
batch 2	92.56	256.43	440.33	163.87	183.90	0.184	0.066	2491.23
batch 3	92.56	329.65	484.27	237.09	154.63	0.155	0.095	2492.99
batch red	92.53	174.70	390.89	82.17	216.19	0.217	0.033	2458.05

Skeletal density is density of the particle excluding the pores. In these experiments the skeletal density is defined by mass of beads and the volume of water they are

replacing. Average skeletal density for clear beads is 2491.91 g/l and weighted average for all the beads in the bed is 2490.8 g/l.

There are 66 450 particles in one kilogram so the number of particles in one batch can be calculated as follows.

$$\begin{aligned} n_{beads} &= m_{beads} \cdot N_{beads \text{ in kilogram}} \\ &= 0.27137 \text{ kg} \cdot 66450 \frac{pcs}{kg} = 18033 \text{ pcs} \end{aligned}$$

If all particles are presumed fully spherical(nonporous) volume of beads can be calculated as follows.

$$\begin{aligned} V_{nonporous \text{ beads}} &= N_{particles} \cdot \frac{3}{4} \pi \left(\frac{d_{particle}}{2} \right)^3 \\ &= 18033 \text{ pcs} \cdot \frac{3}{4} \pi \cdot \left(\frac{0.00227 \text{ m}}{2} \right)^3 \\ &\quad \cdot 1000 \frac{l}{m^3} = 0.110 \text{ l} \end{aligned}$$

With volume of nonporous beads and measured skeletal volume of the beads the void fraction can be calculated. This void fraction describes the volume difference between fully spherical bead and measured bead.

$$\Phi = \frac{V_{nonporous \text{ beads}} - V_{beads}}{V_{nonporous \text{ beads}}} = \frac{0.110 \text{ l} - 0.109 \text{ l}}{0.110 \text{ l}} = 0.0138$$

Dry density used here is defined with mass of beads and volume of beads that are presumed fully spherical. Dry density of beads are calculated as follows.

$$\rho_{dry} = \frac{m_{beads}}{V_{nonporous\ beads}} = \frac{271.37\ g}{0.110\ l} = 2457.13\ g/l$$

Wet density is the density of bead when the water is filling the pores and that is taken in account in particle density. Wet density is calculated as follows.

$$\rho_{wet} = \Phi \cdot \rho_{water} + (1 - \Phi) \cdot \rho_{skeletal\ density} = 0.0138 \cdot 998.324 \frac{g}{l} + (1 - 0.0138) \cdot 2491.52 \frac{g}{l} = 2470.91\ g/l$$

Results of density calculations are presented in Table 2.

Table 2. Density calculations of particles.

	Number of particle	Volume of nonporous beads [l]	Void fraction	Dry density [g/l]	Wet density [g/l]
batch 1	18033	0.110	0.0138	2457.13	2470.91
batch 2	10889	0.067	0.0137	2457.13	2470.79
batch 3	15754	0.096	0.0144	2457.13	2471.49

Average wet density is 2471.1 g/l. The different densities of the painted particles are ignored because less than 0.5 % of the particles in the bed are painted red and the density of painted particles is 2458.1 g/l which is really close to the unpainted particles.

9.2 Liquid phase

The liquid phase used in the experiments is tap water at temperatures varying between 14 – 19 °C.

9.3 Gas phase

The gas phased used in the experiments is pressurized air obtained from 5 bar compressed air line. The air is dried prior to compressing it into 5 bar and fed to the line.

10 Testing equipment installment

The experiments required installation of new equipment to the existing testing setup. This new equipment included new data logging equipment and new gas and liquid flowmeters.

10.1 Data logging equipment installment

New data logging equipment is Keysight/Agilent 34972A LXI Data Acquisition device. In order to obtain the data from the pressure sensors and flow meters an exterior power supply is needed. Before the experiments all the wiring between meters, power supply and data logger were connected. All the meters were connected with two wire connections where the power supply and the transmitter were connected in circuit as illustrated in Figure 10.

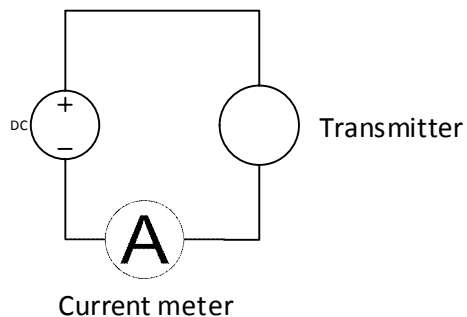


Figure 10. Wiring diagram of transmitters.

10.2 Gas flowmeter installment

The gas flow meter was installed in pipeline with equalizing sections prior to and subsequent to the sensor. Pressurized air was fed from tap along 10 mm inside diameter hose. Hose was connected to the pipe where the flow sensor was installed. The pipe was connected to the column with similar hose used to connect the tap and flow meter pipe. Shut-off valves were installed prior to and subsequent to the pipe section and additionally subsequent to the pipe also non-return valve was installed to prevent water entering the gas flow section.

10.3 Liquid flow meter installment

Liquid flow meter was attached to 40 cm long inlet and outlet pipes. The pipes were connected with 38 mm inside diameter hose to the pump and to the valves that regulates the water flow rate to the column.

During the experiments it was observed that valves regulating the flow velocities generated unwanted disturbance in the liquid flow. In addition, the pump is not running in optimal range which also might produce some disturbance in the flow. The flow became slightly pulse-like causing additional rocking motion in particles and scatter in pressure measurements. This disturbance could be decreased by closing the valve for liquid minimum circulation flow. However this valve cannot be fully closed with low liquid velocities to the column because of the stress resulting for the pump.

11 Results

11.1 Minimum fluidization

Minimum fluidization point were measured by first setting the liquid flow to around 0.075 m/s and then starting the data logging. Then the liquid flow velocity was decreased gradually until the flow was noticeably smaller than visually observed minimum fluidization point.

Minimum fluidization point was defined in these experiments with two pressure sensors 25 cm from each other within the bed. The exact minimum fluidization

point was determined by plotting the pressure drop between the two sensors as a function of the flow velocity. The point where the slope of pressure drop changes is minimum fluidization point. When the superficial liquid flow velocity was defined at minimum fluidization point new measurement for pressure drop and bed height was carried out. The superficial liquid flow velocity was set in constant flow at minimum fluidization point. Then the pressure difference and bed height was measured.

It is worth mentioning that when the pressure drop is measured in two fixed points within the bed, it is required for the calculations to assume that in the whole bed the particles are homogenously distributed. In reality this might not be exactly true since for example near the top of the bed the particle distribution is more uneven and sparse due to bubble interaction and particles thrown into freeboard region.

Especially with higher gas flows the pressure drop – superficial liquid velocity curves from raw data disperse considerably, so that the graphs are really challenging to interpret without data processing as seen in Figure 11.

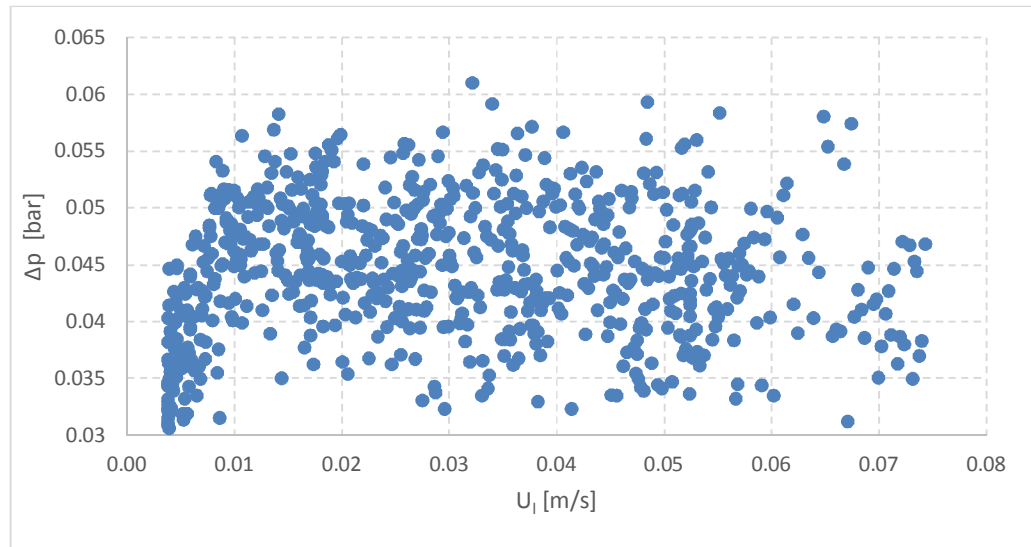


Figure 11. Pressure drop as a function of superficial liquid flow velocity from raw data. Superficial gas flow velocity is 0.034 m/s.

When averaging nine consequent pressure drop and superficial liquid flow velocity measurements the dispersion decreases to some extent. Graph made from these values is presented in Figure 12 with superficial gas velocity of 3.4 cm/s.

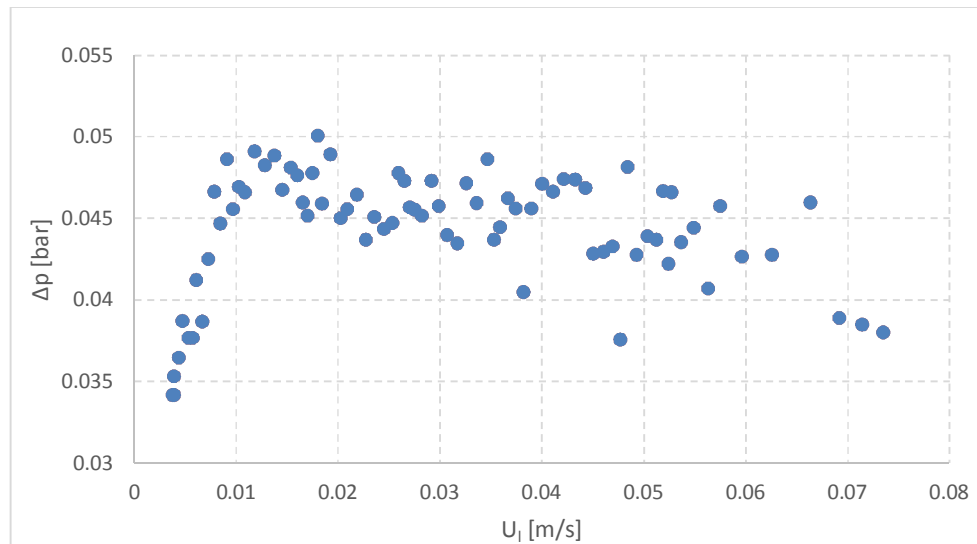


Figure 12. Pressure drop as function of superficial liquid flow velocity from 9 averaged data points.

Data points were divided into groups by superficial liquid flow velocity in 0.001 m/s intervals and taking median of the pressure drops belonging to each group. The median presented pressure drop of each group. By plotting the group median pressure drop as function of intermediate superficial liquid flow velocity value of each group slightly less dispersed graph is formed as seen in Figure 13.

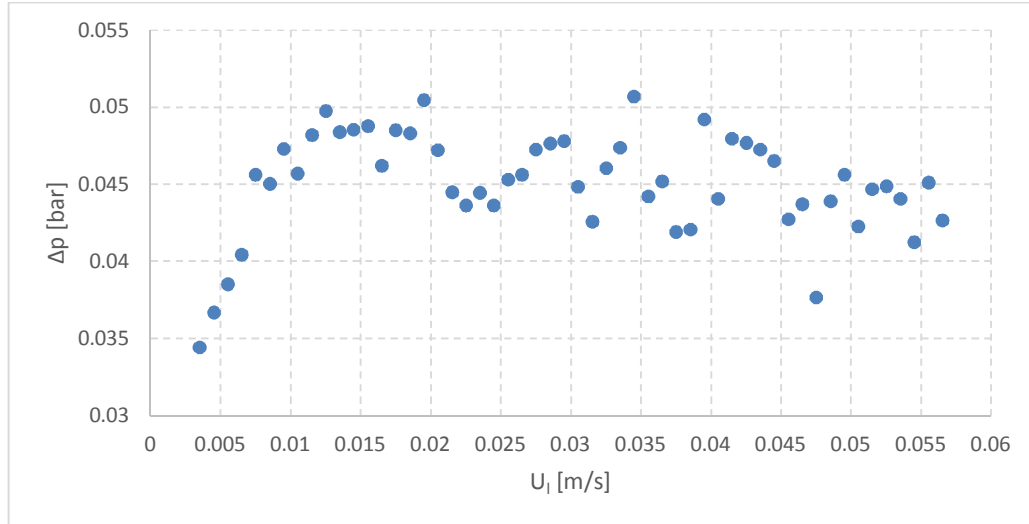


Figure 13. Pressure drop as function of superficial liquid flow velocity with grouping superficial flow velocities.

This grouping method was used to specify the minimum fluidization points i.e. the points where the trend in the each graph changes. The minimum fluidization points were defined with six different gas velocities.

The graph in Figure 14 illustrates superficial velocities of gas and liquid at the minimum fluidization. It is seen in the Figure 14. Superficial velocities at minimum fluidization. It can be seen in the Figure 14 that at the minimum fluidization point the superficial liquid velocity is considerably higher when there is no gas flow or diminutive small gas flow. When the superficial gas flow is higher the superficial liquid velocity at minimum fluidization is rather independent on gas flow rate.

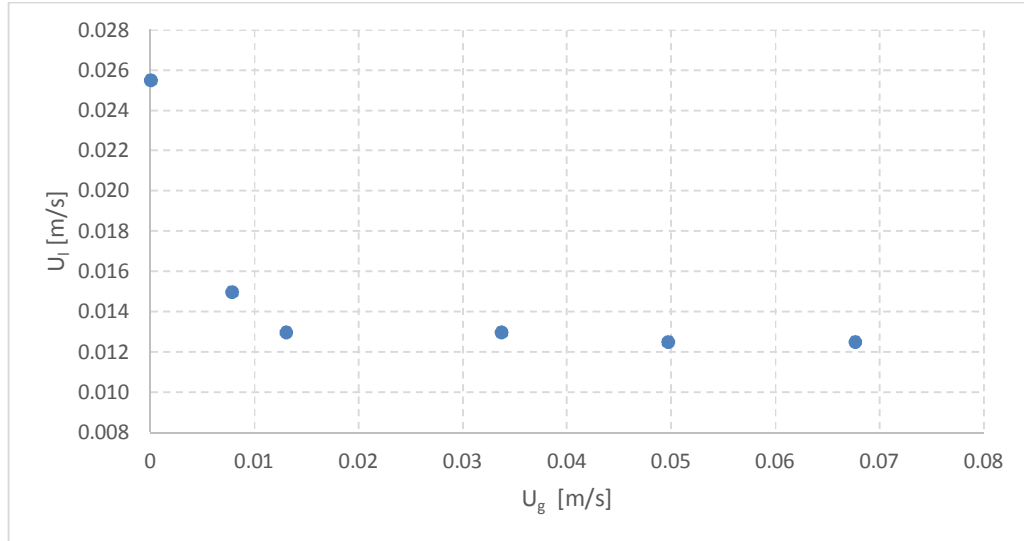


Figure 14. Superficial velocities at minimum fluidization.

At minimum fluidization point the height of the bed was measured and presented in Table 3. The height was measured by taking a photograph from top of the bed. Especially at higher gas velocities the bed level is not even. Therefore, the bed height was defined by reading the bed height from the highest point where the bed level is uniform in horizontal direction as illustrated in Figure 15.

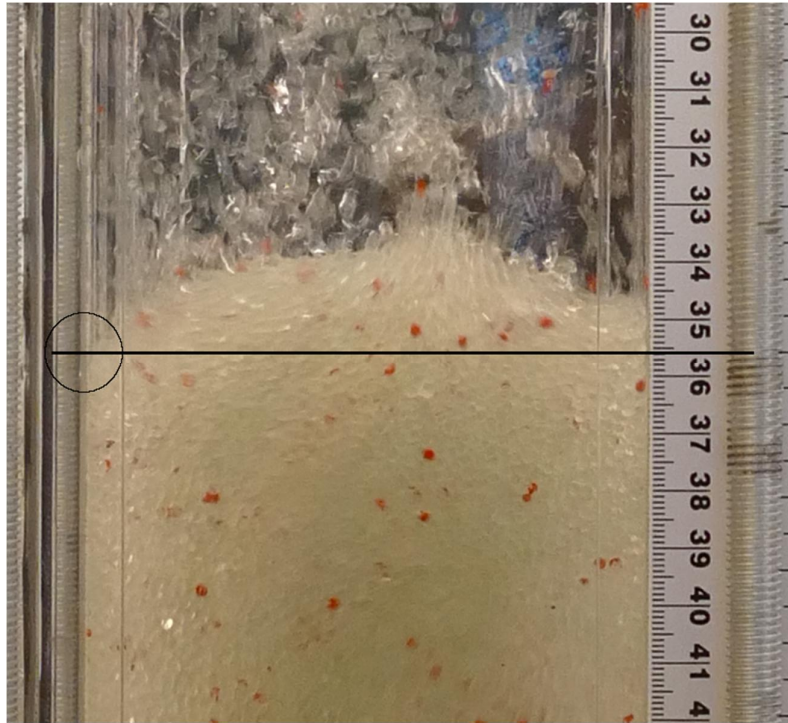


Figure 15. Defining the height of the bed.

Table 3. Bed height in minimum fluidization.

U_g [cm/s]	U_l [cm/s]	bed height [cm]
0.00	2.54	43.6
0.78	1.47	41.7
1.65	1.29	41.8
3.27	1.31	42.3
5.13	1.22	42.8
6.56	1.24	43.5

It was noticed that the bed height at minimum fluidization point was lower than in the fixed state presumably because prior to the minimum fluidization point particles are rearranging and are not yet found the optimal packing structure. Whereas really close to minimum fluidization point the particles are able to rearrange more efficiently so that the bed height decreases to the point until the fluid velocity becomes high enough to start lifting the particles. The fixed bed height is also

dependent on how the expanded bed is lowered to fixed state. If the bed is collapsed the fixed bed height is higher than if it is taken down slowly by increasing fluid flow gradually. The bed that has been gradually taken down the fixed bed height is close to height of the bed at minimum fluidization point. The difference was more than 1 % of the bed height and slightly more than 2 % in solid hold up.

11.2 Hold-ups

Hold-ups express the fraction of specific phase in cross-section of the column. For calculating the solids and gas hold-up equations 10, 11, 12, 13, and 14 were used.

11.2.1 Solids hold-up

When the mass of the particles in the bed, the density of the particles, the cross-section area of the column, and the height of the bed is known the solids hold-up can be calculated with equation 10.

It was discovered that the bed height measurements are not that straightforward and unambiguous since remarkable amount of particles are entrained into freeboard region especially with higher gas flow rates. So visually determining the height of the bed accurately is really challenging.

The height of the bed at minimum fluidization point were measured in different gas velocities. The solids hold-up was then calculated at the minimum fluidization point at different gas velocities.

The mass of the bed was weighted prior to inserting the particles into the column. The density of the particles and the cross-section area of the column was known and the height of the bed was measured from the photographs.

$$\varepsilon_{s,mf} = \frac{W}{\rho_s S H_{mf}} = \frac{6439.6 \text{ g}}{2471.1 \frac{\text{kg}}{\text{m}^3} \cdot 0.01 \text{ m}^2 \cdot 0.436 \text{ m}} = 0.598$$

Solid hold-ups at minimum fluidization point are presented in Table 4.

Table 4. Solid hold-ups in minimum fluidization points.

U_g [cm/s]	U_l [cm/s]	$\epsilon_{s,mf}$
0.00	2.54	0.598
0.78	1.47	0.625
1.65	1.29	0.623
3.27	1.31	0.616
5.13	1.22	0.609
6.56	1.24	0.599

Pressure difference within the bed as well as bed height were also measured for superficial gas velocities of roughly 0, 0.8, 1.6, 3.4, 5.0, and 6.6 cm/s and superficial liquid velocities of roughly 1.4, 2.8, 4.1, 5.5, 7.0, and 8.3 cm/s.

11.2.2 Gas hold-up

Gas hold-up was calculated with equation 14. The results for these calculations are presented in Figure 16. It is evident that there are errors either in experiment data or the calculations since the gas hold-up appears to be negative in most of the data points. However the trend seems to be rather reasonable.

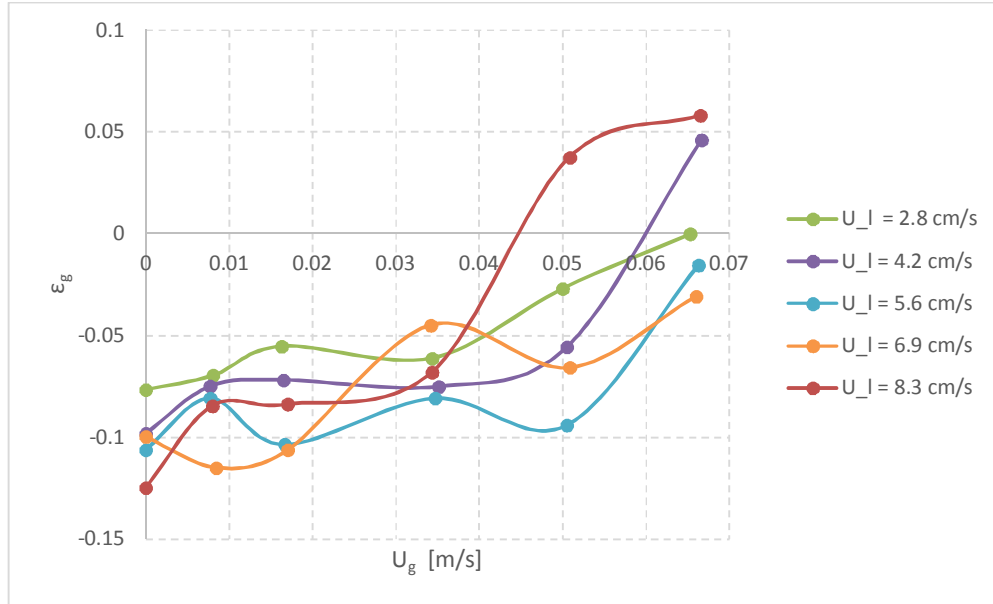


Figure 16. Gas hold-up calculations as a function of superficial gas velocity.

The possible error sources are inaccuracy in defining the bed height, inaccuracies in pressure measurements, variations in liquid temperatures, fouling of the system, and variation in flow velocities. Presumably the major error sources are defining the bed height and pressure measurements. With flow velocities used in these experiments the uncertainty of the bed height measurements can be at worst around 10 % what causes significant uncertainty to gas hold-up calculations. Inaccuracy in bed height measurements increases slightly with increase in liquid flow and considerably with increase in gas flow.

Another major error source is in the pressure measurements. Because the pressure drop within the bed is measured only with two sensors, the conditions in those exact measuring points are defining the pressure drop gradient for the whole bed. However, during the experiments it was noted that in different parts of the bed solid hold-up differ, affecting the pressure drop calculations.

Gas fraction of the whole column was also defined by running column with specific liquid and gas velocities. Then inlet liquid and gas flows as well as outlet liquid flow were simultaneously stopped. Then the decrease in the water level in the top of

the column were measured. The decrease in water level and the accumulated air below distribution plate and top of the column indicated how much air was accumulated in the column. The volume of air was counted and the total volume of the system was measured from which the gas fraction in the whole system was calculated. These results are presented in Figure 17 and in Figure 18.

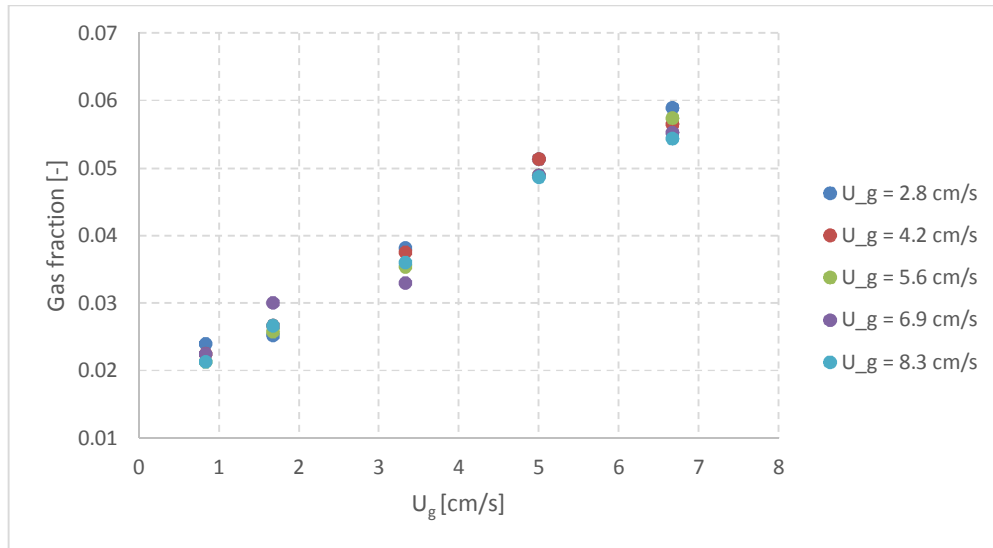


Figure 17. Gas fraction in the column as a function of superficial gas velocity.

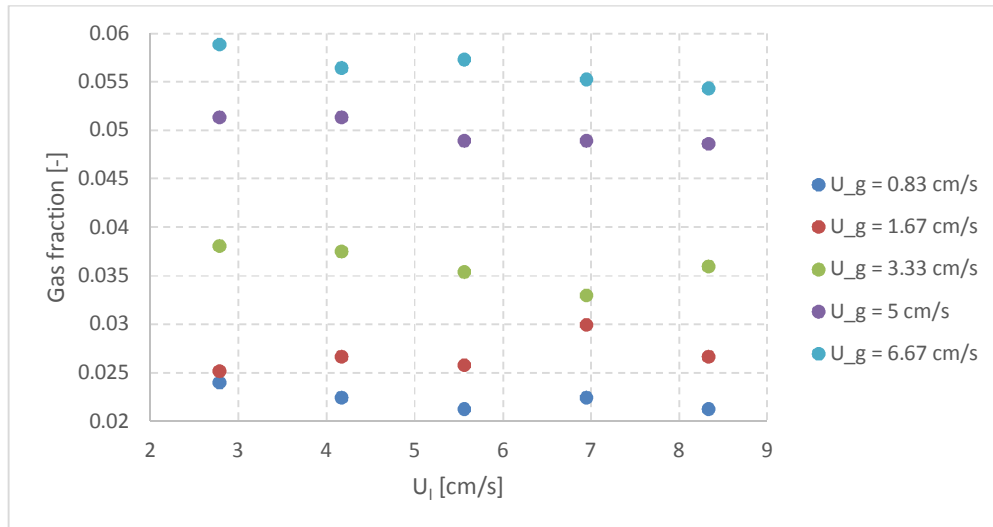


Figure 18. Gas fraction as a function of superficial liquid velocity.

It is seen from Figure 17 that the gas fraction in the column is growing linearly with the superficial gas flow velocity. From Figure 18 it is seen that the effect of superficial liquid flow velocity is rather small to the gas fraction of the column. However, slight downward trend can be observed with gas fraction when the superficial liquid flow velocity is increasing.

11.3 Bed expansion

Bed expansion can be defined from previous solids hold-up measurements as follows.

$$\text{Bed expansion} = \frac{\varepsilon_{s,mf}}{\varepsilon_s} - 1$$

Bed expansion results with different superficial gas and liquid flow velocities are graphed and presented in Figure 19 and in Figure 20.

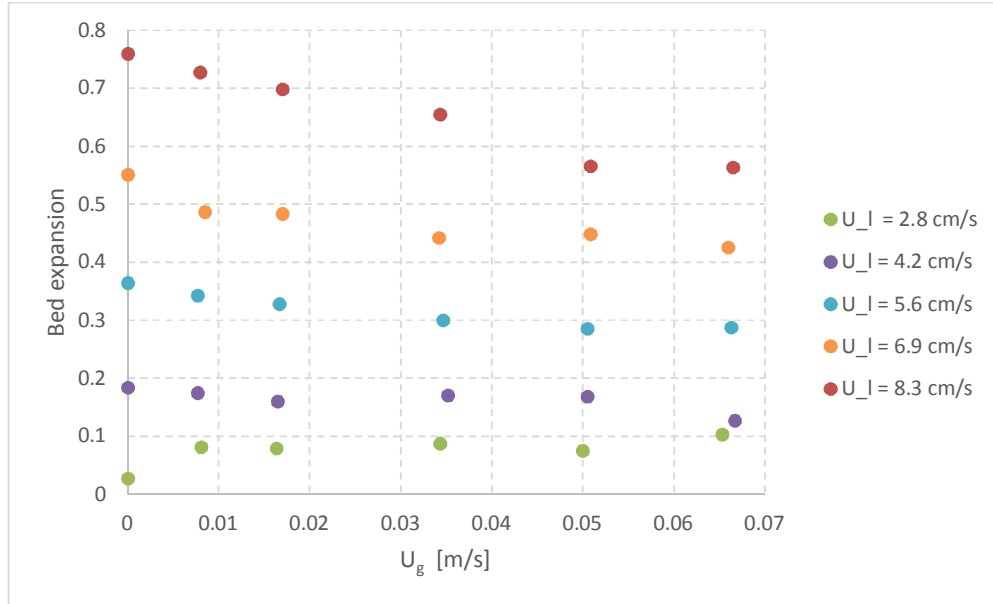


Figure 19. Bed expansion as a function of superficial gas velocity.

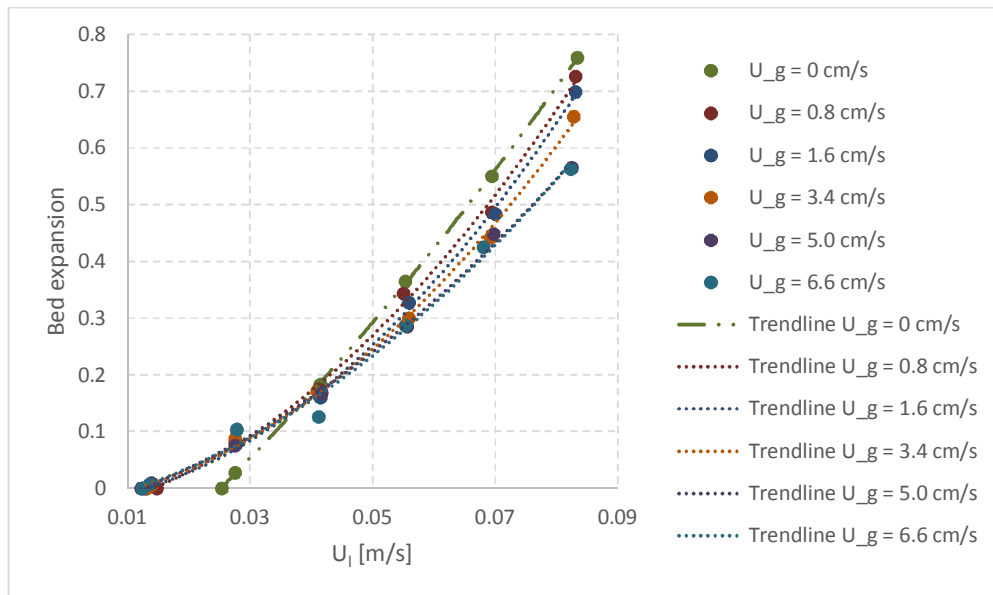


Figure 20. Bed expansion as a function of superficial liquid velocity.

It is seen from the Figure 19 that with lower superficial liquid velocities the expansion is rather independent on the superficial gas velocities. However, when the superficial liquid flow velocity is increased considerably, the increase in superficial gas velocity decreases the bed expansion slightly.

In Figure 20 it is seen that the bed expansion as a function of superficial liquid velocity follows well the polynomic fittings. Another observation from the expansion measurements is that the bed expansion seems to behave differently when there is gas flow to the column compared to the situation where there is only liquid flow. When there is only liquid flow the minimum fluidization point is later than with gas and liquid flow. However, the expansion increases faster when gas flow is not introduced. In consequence there is a point where the bed expansion curves for liquid-gas systems and liquid system are crossing. Nevertheless, the uncertainties in the measurements of the bed height can partly explain these results.

11.4 Particle movement

Particle movement was observed with a video camera in one side of the column. Recording only from one side posed a problem since it was noticed that the flow patterns near the walls were not similar in all sides of the column. By comparing the different sides of the column, channeling could be clearly observed. Consequently, with these methods flow and particle moving patterns could not be comprehensively analyzed even at the vicinity of the column walls.

In the experiments considerable channeling was noticed regardless of the liquid or gas flow velocities. The channeling was observed near the minimum fluidization velocities as well as with much higher fluid flow velocities. When approaching the minimum fluidization point while increasing the fluid flow velocities the particles first started to move in one part of the column cross-section and when increasing the fluid flow velocity further, the particles started to move in all parts of the cross-section and in the channeling parts the movement was considerably faster. Channeling was likely due to the distribution plate design and other column design aspects.

11.4.1 Liquid-solid fluidization

At minimum fluidization point minor particle rocking movement was observed with the particles on the top of the bed as well as just above the distribution plate. When the flow velocity was increased, broader movement of particles was observed. The particles just above the distribution plate were carried up short distances in fluid flow by the walls in center parts of the sides. When particles reached their highest

position they were then pushed to corners and central parts of the column where they started slowly descending as illustrated in Figure 21. In upper parts of the column the particles were moving considerably slower than in the lower parts of the column near the distribution plate.

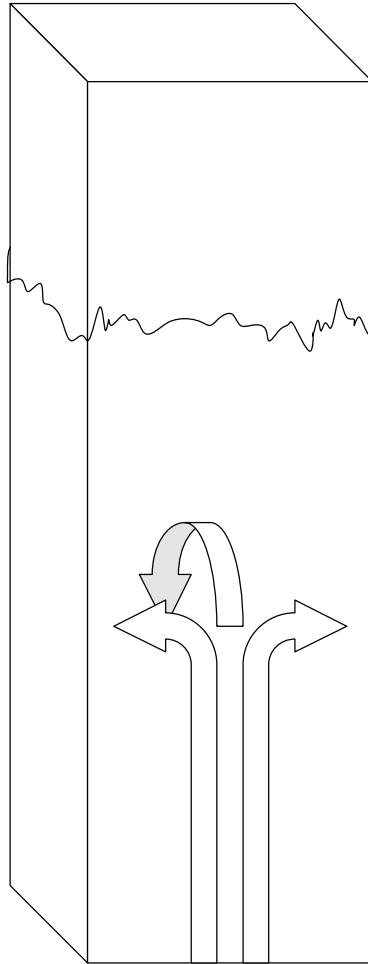


Figure 21. Particle flow pattern above the minimum fluidization point.

When the liquid flow velocities were increased, the flow pattern seemed to alter slightly. Particles still seemed to have greater upward velocity near the distribution plate by the walls in center parts of the sides however after traveling short distances the rapidly upward moving particles were shifted towards corners where they continued moving rapidly upwards as illustrated in Figure 22. Since the flow was rather channeled, considerable turbulent motion of the particles were observed.

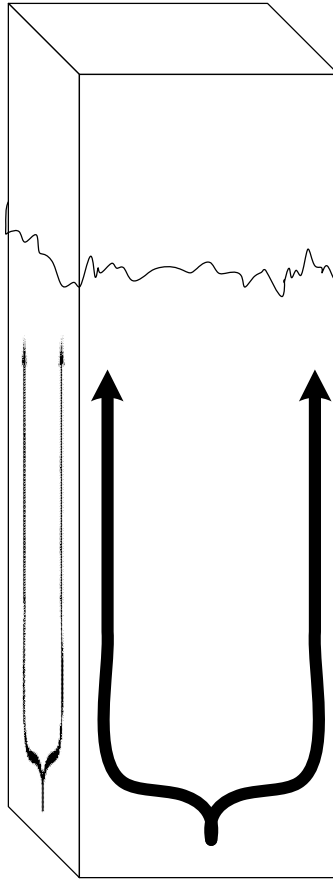


Figure 22. Particle flow pattern at higher superficial liquid flow velocities.

With slower liquid velocities the rapid particle movement was limited to the lower parts of the column. However, when the liquid flow velocity was increased also the particles in the higher parts of the column started to move more rapidly.

When the particle movement in the bed was observed with bright light behind the column, variations in particle density within the bed was observed. As seen in Figure 23 the density variation is seen as brighter horizontal lines in the bed. The density variations in the bed were moving upwards in the bed. New density variations in the bed are forming continuously near the distribution plate.

This wavelike motion phenomena was observed more strongly with higher liquid flow velocities but was also observed with lower liquid velocities. When the gas

flow was introduced to the system, the bubbles moving up in the bed caused these wave motion -like density variations to disappear.

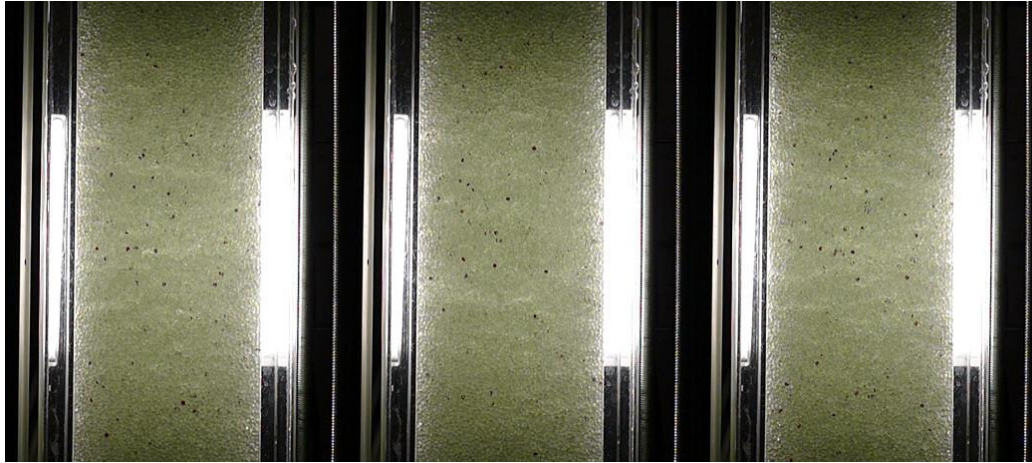


Figure 23. Particle density variation in the bed.

11.4.2 Gas-liquid fluidization

Due to the observation method chosen for these experiments, analyzing the bed behavior was rather limited. As a consequence, the used particle movement analyzing methods were concentrated on the flow regime identification and bubble distribution in the bed. Both of these were determined by analyzing high speed video recordings. In the recordings the superficial liquid velocities used were 1.3 - 8.3 cm/s and used superficial gas velocities were 0 - 6.6 cm/s.

Only with visual observation the demarcation of the regimes was difficult especially between coalesced bubble and slug flow regime because there was no unambiguous point that was visually observable. Also when only observing the column visually demarcation between churn turbulent and slug flow was challenging since the differences are relatively small. Defining the regimes was also challenging because of the visibility in the bed was limited so it was only possible to observe the bubble size and size distribution in the freeboard region.

The regime demarcations rules applied here were considering mostly the bubble sizes and the appearing frequency of specific size of bubbles. Only two flow

regimes were identified with used gas and liquid flow velocities: the coalesced bubble flow regime and the slug flow regime.

Demarcation rule used here between dispersed bubble flow and coalesced bubble flow was based on the bubble sizes. If bubbles were rather small and uniform in size, the regime was dispersed bubble flow regime. Whereas if there were multiple larger bubbles along with smaller bubbles, the regime was coalesced bubble flow. Demarcation between coalesced bubble flow and slug flow regime was vaguer. The rule used here to separate coalesced bubble flow and slug flow regime was that if there were only one large bubble at the time, it was slug flow and if multiple, the regime was considered to be coalesced bubble flow.

Results are presented in Figure 24. In the figure x marks coalesced bubble flow regime, + marks slug flow regime and – marks transition between coalesced bubble flow and slug flow regime. The line below the marks expresses the demarcation between fluidized and fixed state.

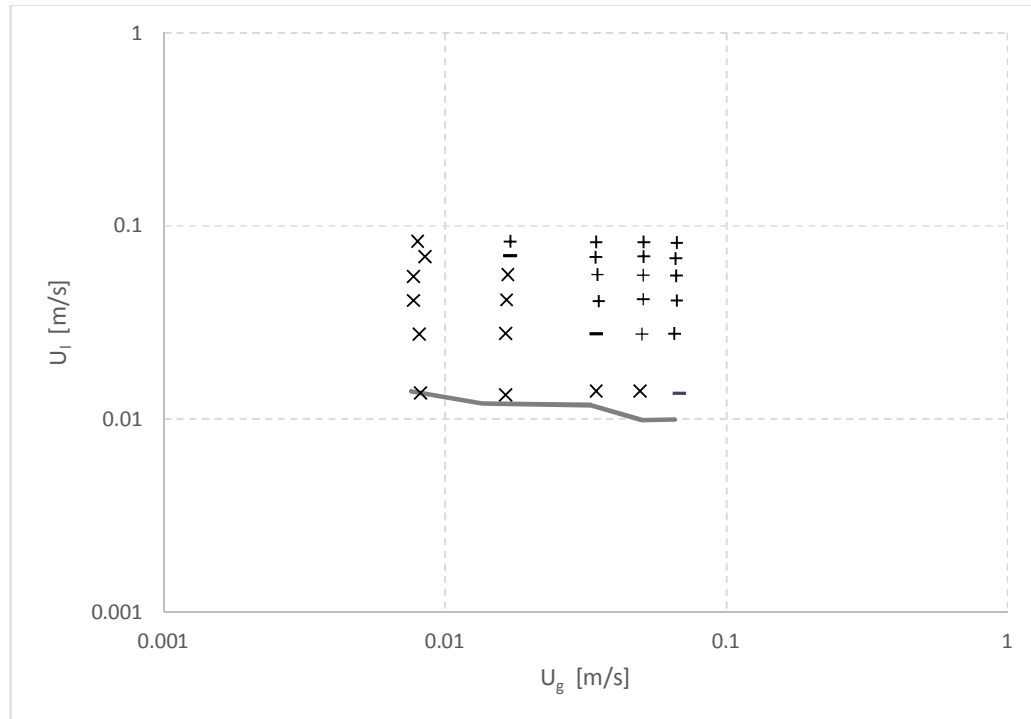


Figure 24. Flow regimes with different superficial gas and liquid flow velocities.

The transition trend between coalesced bubble flow and slug flow is not exactly in line with results of Zhang et al. show in Figure 25 [9]. However the methods used to evaluate the transition between the regimes are different and also because the regime map is strongly dependent on the distribution plate and column design and particles, liquid and gas used in experiments. In the experiments of Zhang et al. the used column was circular with 8.26 cm diameter and the particles were 1.5 mm glass beads. Consequently some of the differences may be explained with these.

Because of the intensive bubble coalescence the flow regions described in paragraph 3.2 were interrupting the flow patterns characteristic to vortical-spiral flow regime. Consequently, the sub-regime of the coalesced bubble regime seemed to be turbulent flow regime.

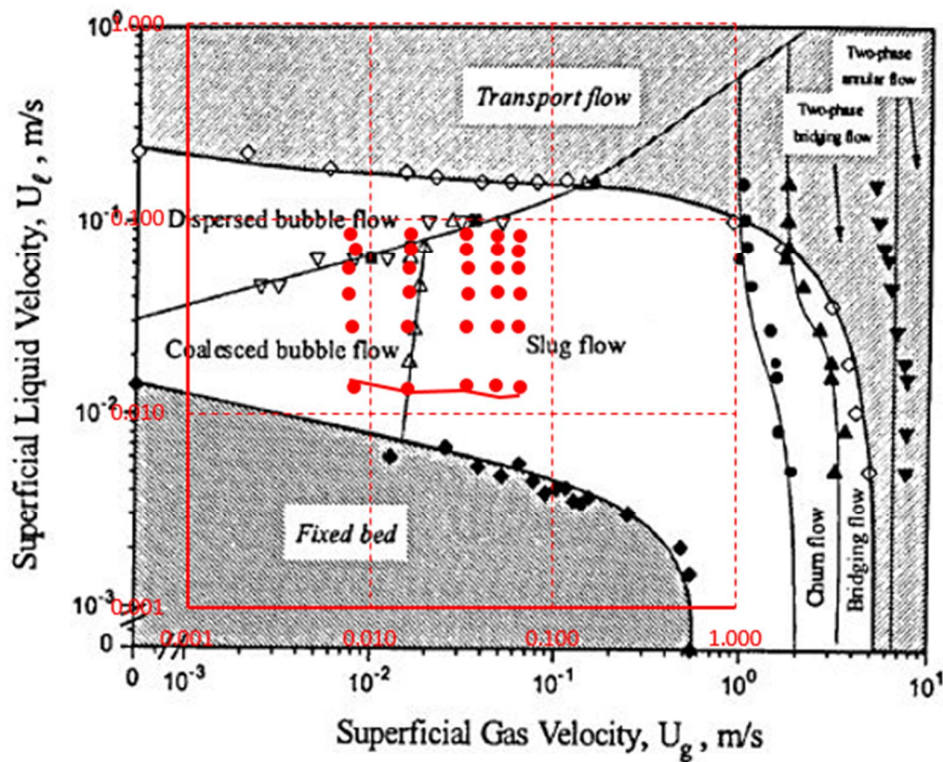


Figure 25. Flow regime map for 1.5mm glass particles[9] and measured data points.

The particle movement velocities appear to be more dependent on the liquid flow velocity than on the gas flow velocity. Whereas the bubbles seems to cause more disordered movement which results in stronger mixing of the particles. This phenomenon resembles strongly the wake model: bubbles moving up form a wake behind the bubble. Particles in the bed are sucked into the wake and moved upwards behind the bubble. And when a bubble reaches the surface of the bed some particles are thrown into freeboard region.

From the experiments it is also observed that the bubble distribution in the column is depending on the superficial gas flow velocity. With lower gas velocities the bubbles are distributed more evenly along the whole bed so that the bubbles are observed also near the column walls. However, with higher gas velocities the bubbles are not observed in the vicinity of the wall as frequently as with lower gas velocities indicating that bubbles tends to concentrate more on central parts of the column with the increase of gas flow velocity. In addition, regardless of the flow velocities the bubbles tend to be more visible near the distribution plate. And when going further away from the plate the amount of bubbles appearing in the vicinity of the walls decreases.

12 Recommendations for improvements and future work

Here are some possible improvements that were discovered during the experiments. Some of these improvements are general and some only for the column used in these experiments.

12.1 Particles motion detection and tracking

With experiment setting like the one used in this thesis it would be rather easy to follow and obtain the movement data of the colored tracer particles. Because usually the flow pattern in the column is not symmetrical so for comprehensive data from the vicinity of the wall it is necessary to recording all sides of the column. However with video recording methods the particle movement deeper in the bed is, especially with air-water-glass combination, still almost impossible to see.

For analyzing the recordings and to obtain movement data motion detection software is needed. It is possible to build particle tracking program for example with help of OpenCV library. For accurate movement detection and particle tracking it is crucial to have video with high frame rate and high resolution.

12.2 Refractive index matching

For future experiments refractive index matching technics would be worth looking into especially if the future experiments are concerning the particle movement. With air-water-glass bead –system the particles are only able to be observed closer than approximately one centimeter away from the column walls. Choices for refractive index matching are to change the particles to match the liquid or to change or alter the liquid to match the refractive index of the particles.

12.3 Observing all sides of the column

The particles movement were recorded only on one side of the rectangular column. However it was clear when visually observed that the flow patterns are dissimilar in other sides of the column. For more accurate analysis it would be necessary to record all sides simultaneously. This could be possible for example setting mirrors so that one camera can record all sides simultaneously or just simply by recording with multiple cameras.

12.4 Paint for tracking particles

In the experiments done for this thesis the tracer particles were marked just by painting them with general spray-paint. However the particles in the bed are undergoing rather severe conditions so that the paint in the particles is gradually peeling off during the experiments. For future experiments it would be worth looking into what kind of paint would be more resistant for wearing.

12.5 Defining the height of the bed

One of the factors generating inaccuracy to the bed expansion measurements was the difficulty in defining the exact bed height of the fluidized bed. The visual observation for accurate measurements was noticed to be inadequate method since especially with higher superficial gas flow velocities the particle entrainment

to the freeboard region is so substantial that the bed level appears to be varying all the time.

Because the axial dynamic pressure distribution has linear behavior in both fluidized bed and freeboard region above the bed, the bed height can be defined from pressure measurements. These measurements requires at least 4 pressure sensor altogether, two in freeboard region and two within the bed. The point where these pressure profiles intersect is the point where the bed level is.[1]

12.6 Bubble size measurements

With the experiment setup used, it was really difficult to assess the bubble sizes and size distribution in the bed. So in future studies it would be worthwhile to use tools such as conductivity probe to obtain more comprehensive data of the bubbles. With conductivity probe it is possible to obtain data of for example bubble frequency, bubble size, bubble velocity, bubble shape, and to use in calculating the gas hold-up[9].

12.7 Gas and liquid valves

During the experiment there were problems with both gas and liquid valves which regulate the flow to the column.

Problem with liquid valves was that they were causing unwanted disturbance in the liquid flow. The problem was caused by the way valves were installed. There were two valves connected to the hose so that the hose coming from pump was connected to the T-fitting. Opposite side of the T-fitting was valve that regulated the flow to the column and to the T-fitting connector not in line with others were connected another valve that regulated the flow straight back to the liquid tank. During the experiments it was noted that when the valve to the tank was open, this valve setting caused severe disturbance in the flow resulting uneven flow to the column, consequently causing considerable disturbance in the pressure measurements.

These problems can be diverted by changing the valves for more suitable ones. As a short term solution, the valve to the liquid tank can be closed but it increases

the stress to the pump especially with low superficial flow velocities in the column. The valves used had also some controllability challenges. So by replacing the valves by valves that are easier to control would even more advantageous.

The valve in the gas line was problematic because it was really sensitive so that adjusting the desired flow rate was difficult. On top of that the gas flow coming from the line was intermittent irregular which made it even more challenging to adjust constant desired flow rate. These problems can be averted to install more sensitive or possibly automatic valves.

12.8 Homogenize the liquid and gas flows and reducing the sizes of bubbles entering the bed

Even if the column has 50 cm long homogenizing section the uneven velocity distribution below the distribution plate was observed. This might be due to the method how the liquid hose is connected to the column. Just below the column there is T-fitting where the flowing liquid makes 90 degree turn. By altering this connection the liquid flow might become more uniform. The calming section can be made more effective also by filling it with packing. The packing will equalize the flow profile prior to the bed.

Another unwanted feature of the column is the gas distribution nozzle. The bubbles leaving the nozzle are not distributed evenly to the whole column area and the generated bubble sizes are rather nonuniform. Desired situation would be that the bubbles were small, uniform in size and distributed evenly along the column cross-section. By changing the design of the nozzle it would be possible to affect the bubbles generated and the distribution of them.

12.9 Reduce column shaking

Especially with high gas and liquid flows quite severe column shaking was observed. This might be due to the turbulence in the column. And because the attachment is not as sturdy as hoped causing the shaking to be more intensive than desired. The shaking may cause some interference to the pressure measurements which causes the interpreting of measured data slightly more

challenging. The shaking may be reduced by installing the column to sturdier mount.

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